

## Differential problem

$$Lu = f \quad \mathbf{x} \in \Omega \subset \mathbb{R}^d$$

**Solvability:** We can access samples  $u(\mathbf{x})$  for a given  $f$  and any  $\mathbf{x} \in \Omega$  at any time (via classical differential equation solvers).

**Operator learning:** We are interested in the solution mapping  $\mathcal{G}(f) = u$ .

## Parametrization of $f$

$$f(\mathbf{x}) \approx \sum_{j=1}^n a_j A_j(\mathbf{x}) \quad \mathbf{x} \in \Omega$$

**Functions:** We use fixed functions  $A_j, j = 1, \dots, n$ , e.g., B-splines or trigonometric polynomials.

**Coefficients:** We identify  $f$  by its coefficients  $\mathbf{a} = (a_1, \dots, a_n) \in \mathbb{C}^n$ .

## Basis expansion of $u$

$$u(\mathbf{x}, \mathbf{a}) := \sum_{\mathbf{k} \in \mathbb{N}^{d+n}} c_{\mathbf{k}} \Phi_{\mathbf{k}}(\mathbf{x}, \mathbf{a}) \quad (\mathbf{x}, \mathbf{a}) \in \mathcal{D}.$$

**Bounded orthonormal product basis:** The  $\{\Phi_{\mathbf{k}}(\cdot), \mathbf{k} \in \mathbb{N}^{d+n}\}$  are bounded, orthonormal and of tensor-product structure, e.g., trigonometric or Chebyshev polynomials.

## High-dim. approximation

$$S_I^A u(\mathbf{x}, \mathbf{a}) := \sum_{\mathbf{k} \in I} \hat{u}_{\mathbf{k}} \Phi_{\mathbf{k}}(\mathbf{x}, \mathbf{a})$$

**Index set:**  $I \subset \mathbb{N}^{d+n}$  is unknown, but  $s$ -sparse, i.e.,  $|I| = s$ .

**Coefficients:**  $\hat{u}_{\mathbf{k}} \in \mathbb{C}$  are approximations of the true coefficients  $c_{\mathbf{k}}$ .



## Main challenge

**Unknown index set:** If  $I$  was known, we could compute the  $\hat{u}_{\mathbf{k}}$  directly and efficiently.

**Search space:** We consider a reasonable search space  $\Gamma \subset \mathbb{N}^{d+n}$  and assume  $I \subset \Gamma$ . However, we have  $|\Gamma| \gg |I|$ .

**Curse of dimensionality:** Computing all  $\hat{u}_{\mathbf{k}}$  with  $\mathbf{k} \in \Gamma$  is computationally unfeasible!

## Algorithm Input

- ▶ search space  $\Gamma \subset \mathbb{N}^{d+n}$
- ▶ sparsity  $s \in \mathbb{N}$
- ▶ detection threshold  $\delta > 0$
- ▶ detection iterations  $r \in \mathbb{N}$
- ▶ target function  $u$  as black box ( $\rightarrow$  PDE solver)

## Dimension-incremental Algorithm<sup>[1]</sup>

- ▶ Works by detecting “good” index sets in lower dimensions and combining them.
- ▶ Utilizes cosine-transformed multiple rank-1 lattices.<sup>[2]</sup>
- ▶ Complexities (with  $\tilde{d} = d + n$  and superposition dimension  $d_s$ ):
  - ▶ Sampling compl.:  $\mathcal{O}(\tilde{d} r^3 s^2 2^{d_s} \log(rs))$
  - ▶ Computational compl.:  $\mathcal{O}(\tilde{d} r^3 s^2 d_s^2 2^{d_s} \log^5(rs))$

## Algorithm Output

- ▶ detected index set  $I \subset \Gamma$  with  $|I| = s$
- ▶ approximated coefficients  $\hat{u}_{\mathbf{k}}$  with  $|\hat{u}_{\mathbf{k}}| \geq \delta$ .

## Poisson equation (1D)

**Differential equation:**

$$-\frac{d^2}{dx^2} u(x) = f(x) \quad x \in (0, 1)$$

$$u(0) = u(1) = 0$$

**Parametrization:**

$$f(x) \approx \sum_{\ell=-(n-1)/2}^{(n-1)/2} a_{\ell} e^{2\pi i \ell x}$$

**Remarks:** We set  $n = 9$ , restricted  $a_{\ell} \in [-1, 1]$  and used the analytical solution instead of a solver.

**Transfer learning:**

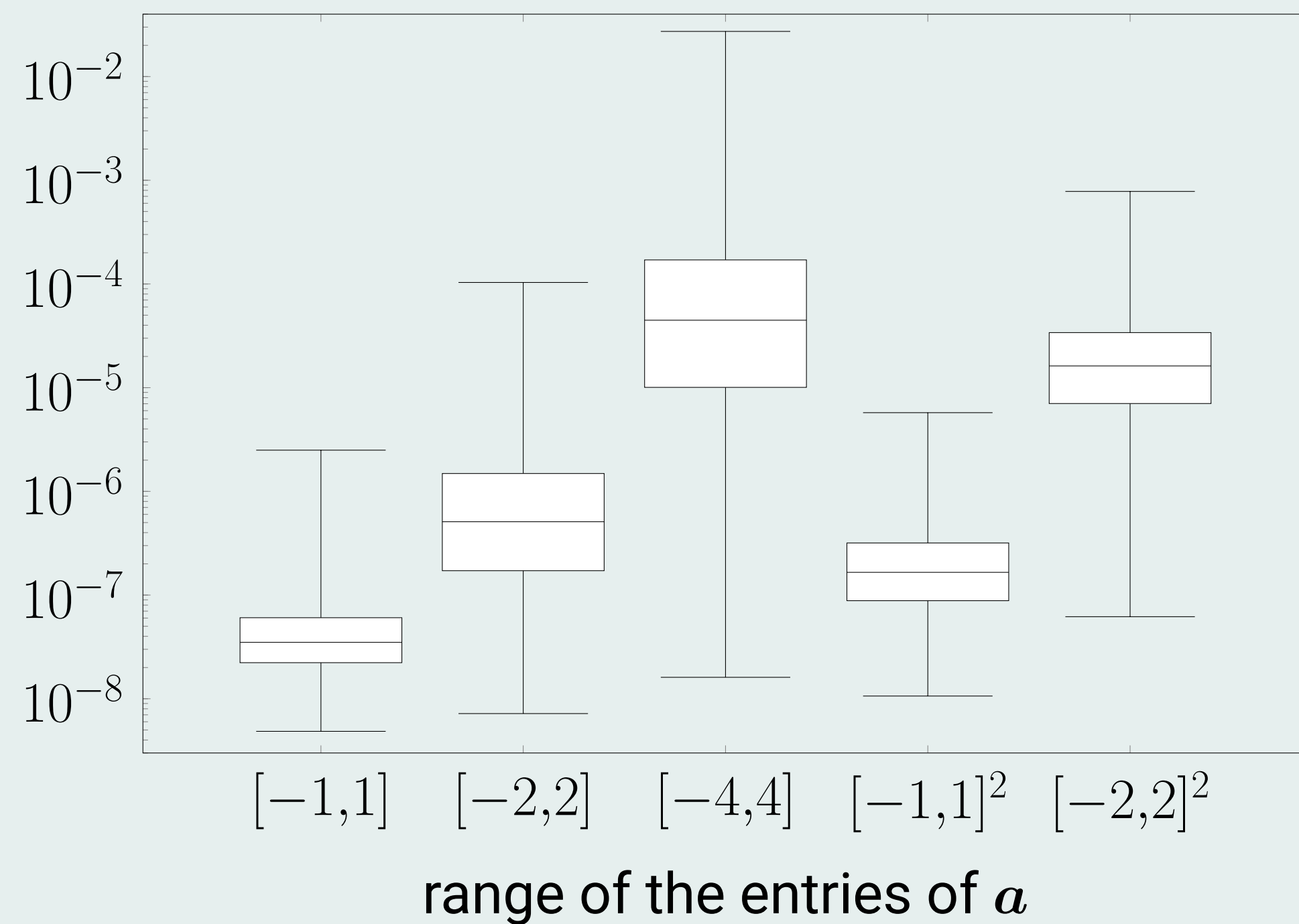


Figure: The relative approximation error for 10000 randomly drawn  $\mathbf{a}$ .

## Poisson equation (2D)

**Differential equation:**

$$-\Delta u(\mathbf{x}) = f(\mathbf{x}) \quad \mathbf{x} \in \Omega$$

$$u(\mathbf{x}) = 0 \quad \mathbf{x} \in \partial\Omega$$

**Parametrization:**

$$f(\mathbf{x}) \approx \sum_{\ell \in J} a_{\ell} e^{2\pi i \ell x}$$

**Remarks:** We used a FEM (1893 nodes) and set  $J = \{-1, 0, 1\}^2$ .

**Average relative approximation error:**  $\approx 10^{-4}$

**Structural information:**

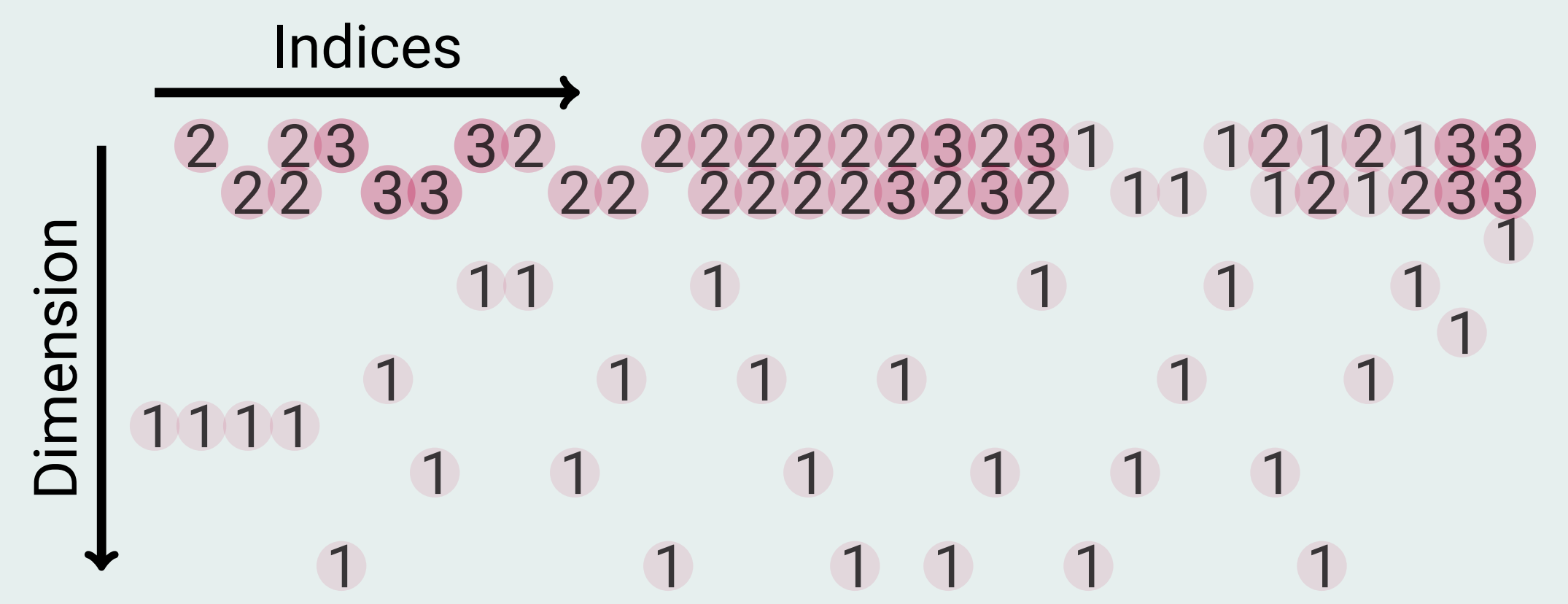


Figure: The first 30 indices detected.

## Heat equation

**Differential equation:**

$$\partial_t u = \alpha^2 \partial_{xx} u \quad x, t \in (0, 1)$$

$$u(x, 0) = f(x) \quad x \in (0, 1)$$

$$u(0, t) = 0 \quad t \in (0, 1)$$

$$u(1, t) = 0 \quad t \in (0, 1)$$

**Parametrization:**

$$f(x) \approx \sum_{\ell=1}^n a_{\ell} \sin(\ell \pi x)$$

**Remarks:** We set  $n = 9$  and used the MATLAB<sup>®</sup> function pdepe.

**Average relative approximation error:**  $\approx 10^{-3}$

**Structural information:**

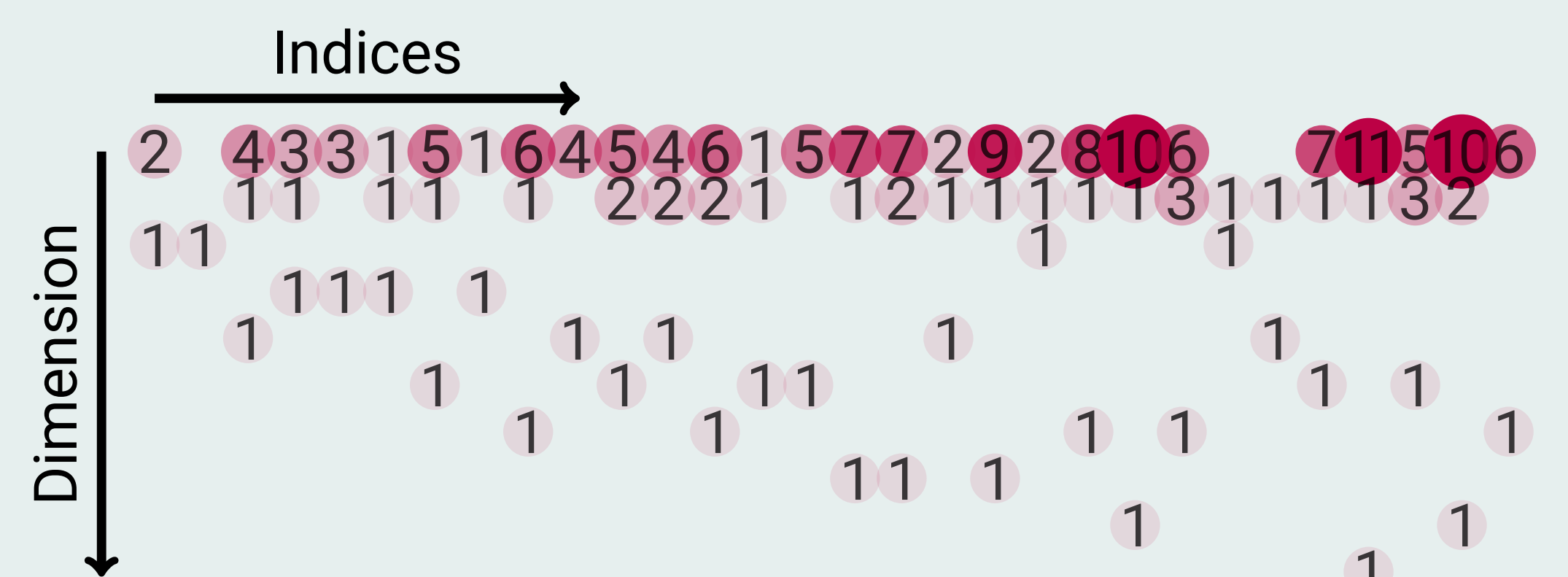


Figure: The first 30 indices detected.

[1] L. Kämmerer, D. Potts and F. Taubert. Nonlinear approximation in bounded orthonormal product bases. *Sampl. Theory Signal Process. Data Anal.*, 2023.  
[2] L. Kämmerer. An efficient spatial discretization of spans of multivariate Chebyshev polynomials. *arXiv preprint*, 2024.  
[3] D. Potts and F. Taubert. Operator learning based on sparse high-dimensional approximation. *arXiv preprint*, 2024.

