

# The uniform sparse FFT

with application to PDEs with random coefficients

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joint work with Lutz Kämmerer and Daniel Potts

11.02.2022



TECHNISCHE UNIVERSITÄT  
CHEMNITZ

## 1. Introduction

Setting

The sparse FFT

## 2. The uniform sparse FFT

The key idea

Main result

## 3. Numerical examples

Affine random coefficient

Lognormal random coefficient

We consider the PDE problem

$$\begin{aligned}
 -\nabla_{\mathbf{x}} \cdot (a(\mathbf{x}, \mathbf{y}) \nabla_{\mathbf{x}} u(\mathbf{x}, \mathbf{y})) &= f(\mathbf{x}), & \mathbf{x} \in D, \mathbf{y} \in D_{\mathbf{y}} \\
 u(\mathbf{x}, \mathbf{y}) &= 0, & \forall \mathbf{x} \in \partial D, \mathbf{y} \in D_{\mathbf{y}}.
 \end{aligned}$$

- ▶ spatial variable  $\mathbf{x} \in D \subset \mathbb{R}^{d_{\mathbf{x}}}$ , typically with  $d_{\mathbf{x}} = 1, 2, 3$
- ▶ random variable  $\mathbf{y} = (y_j)_{j=1}^d \in D_{\mathbf{y}}$ , typically very high-dimensional or even infinite-dimensional

- ▶ **affine random coefficient** [Cohen, DeVore, Schwab '10], [Dick, Kuo, Le Gia, Schwab '16], [Bachmayr, Cohen, Dahmen '18], [Gantner, Herrmann, Schwab '18], [Nguyen, Nuyens '21], ...

$$a(\mathbf{x}, \mathbf{y}) = a_0(\mathbf{x}) + \sum_{j=1}^d y_j \psi_j(\mathbf{x})$$

- ▶ **periodic random coefficient**

[Kaarnioja, Kuo, Sloan '20], [Kaarnioja, Kazashi, Kuo, Nobile, Sloan '20]

$$a(\mathbf{x}, \mathbf{y}) = a_0(\mathbf{x}) + \sum_{j=1}^d \Theta_j(\mathbf{y}) \psi_j(\mathbf{x}),$$

with  $\Theta_j$  periodic, e.g.,  $\Theta_j(\mathbf{y}) := \frac{1}{\sqrt{6}} \sin(2\pi y_j)$

- ▶ **lognormal random coefficient** [Graham, Kuo, Nichols, Scheichl, Schwab, Sloan '13], [Cheng, Hou, Yan, Zhang '13], [Bachmayr, Cohen, DeVore, Migliorati '17], [Nguyen, Nuyens '21], ...

$$a(\mathbf{x}, \mathbf{y}) = a_0(\mathbf{x}) + \exp(b(\mathbf{x}, \mathbf{y})), \quad b(\mathbf{x}, \mathbf{y}) = b_0(\mathbf{x}) + \sum_{j=1}^d y_j \psi_j(\mathbf{x})$$

- ▶ Common aim: Approximation of the solution  $u(\mathbf{x}, \mathbf{y})$  or some quantity of interest, e.g., the expectation value  $\mathbb{E}[F(\mathbf{y})]$  of some functional  $F(\mathbf{y}) := F[u(\cdot, \mathbf{y})]$ , using samples of the function.
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- ▶ Examples of other approaches:
  - ▶ Quasi-Monte Carlo methods  
[Kuo, Schwab, Sloan '15], [Dick, Le Gia, Schwab '16], [Nguyen, Nuyens '21], ...
  - ▶ collocation methods  
[Cheng, Hou, Yan, Zhang '13], [Ernst, Sprungk '14], [Zhang, Hu, Hou, Lin, Yan '14], ...
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- ▶ These approaches are often heavily influenced by the choice (or computation) of some weights, functions or kernels in advance!

- ▶ We aim for an approximation of  $u(\mathbf{x}_0, \cdot)$  for fixed  $\mathbf{x}_0 \in D$  using the sparse FFT (sFFT) based on rank-1 lattice sampling.

[Potts, Volkmer '16], [Kämmerer, Kraemer, Volkmer '20], [Kämmerer, Potts, Volkmer '21]



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- ▶ The goal of the sFFT is the computation of the index set  $I = \text{supp } \hat{p} \subset \mathbb{Z}^d$  in the given search space  $\Gamma \supset I$  and the coefficients  $\hat{p}_{\mathbf{k}}, \mathbf{k} \in I$ , of the multivariate trigonometric polynomial

$$p(\mathbf{y}) = \sum_{\mathbf{k} \in I} \hat{p}_{\mathbf{k}} e^{2\pi i \mathbf{k} \cdot \mathbf{y}}$$

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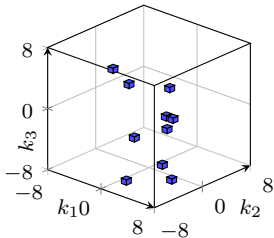
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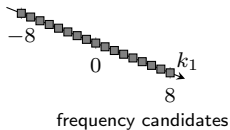
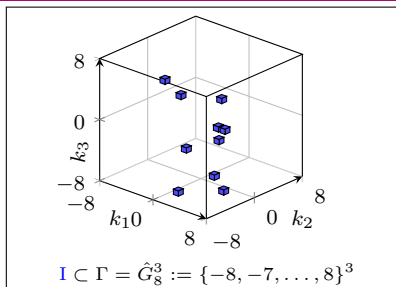
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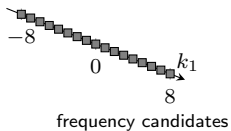
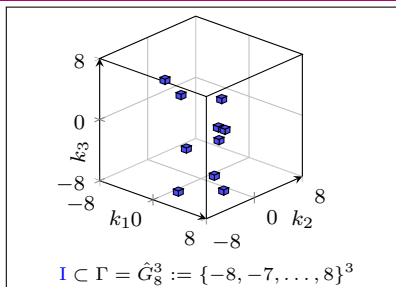
- ▶ Function approximation of  $u(\mathbf{x}_0, \cdot)$  can be realized using the sFFT by assuming it to be a trigonometric polynomial  $p$  with some noise  $\eta$ , i.e.,

$$u(\mathbf{x}_0, \mathbf{y}) = p(\mathbf{y}) + \eta(\mathbf{y}).$$

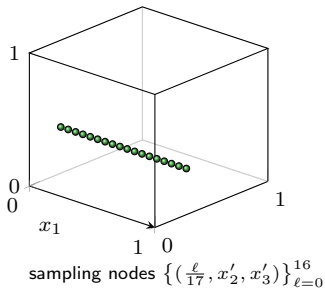


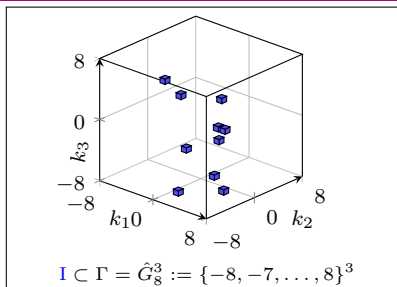
$$I \subset \Gamma = \hat{G}_8^3 := \{-8, -7, \dots, 8\}^3$$





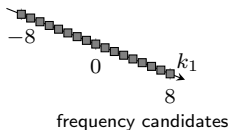
construct  
→  
sampling set



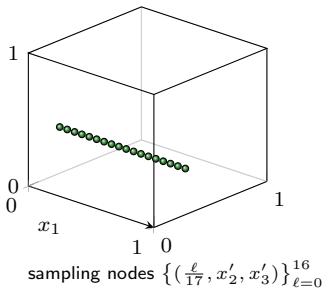


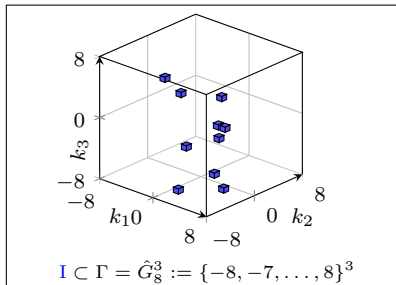
$$\hat{p}_{k_1} := \frac{1}{17} \sum_{\ell=0}^{16} p \left( \begin{pmatrix} \ell/17 \\ x'_2 \\ x'_3 \end{pmatrix} \right) e^{-2\pi i \frac{\ell k_1}{17}}$$

$$k_1 = -8, \dots, 8$$



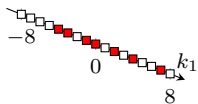
1-dim.  
←  
FFT





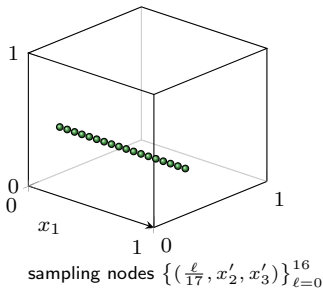
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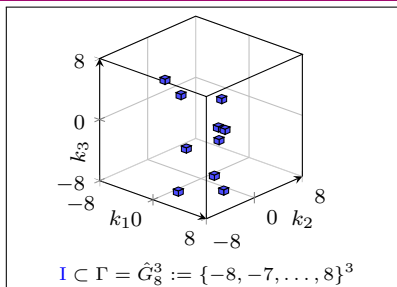
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detected frequencies  $I^{(1)}$

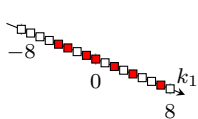
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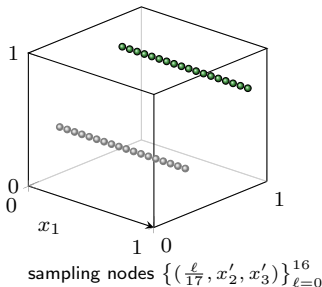


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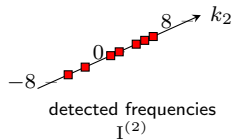
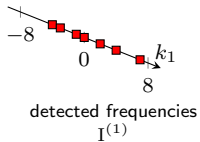
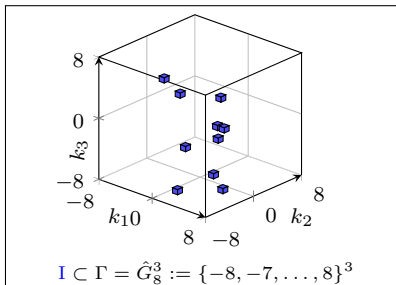


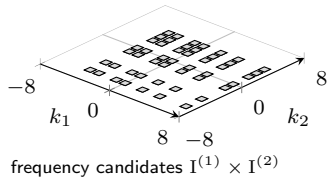
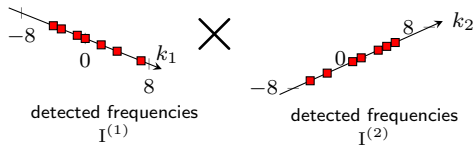
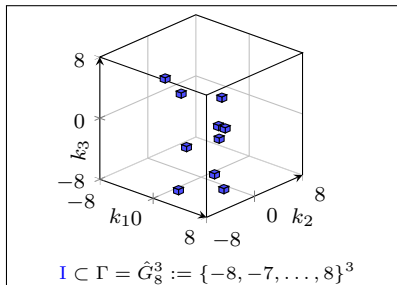
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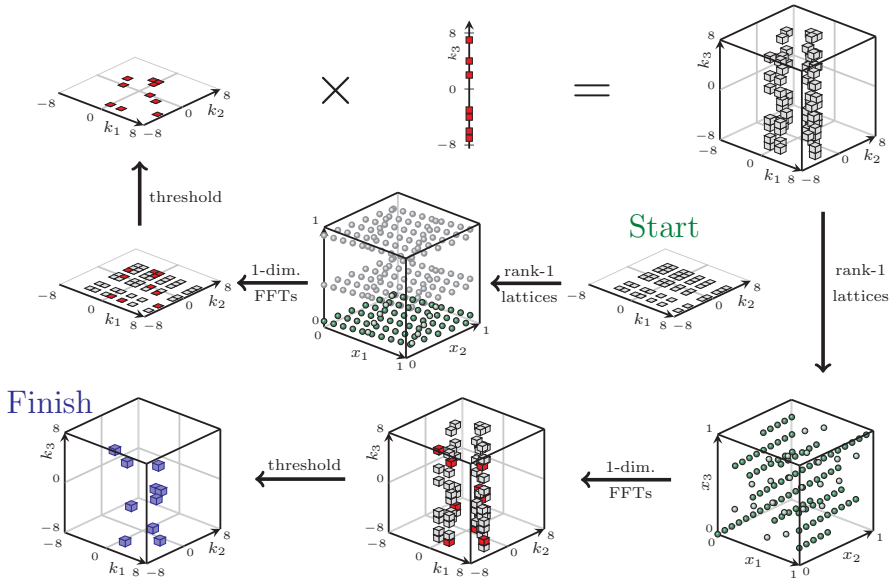


+ repeat ( $r$  detection iterations)









- ▶ Back to our original problem:  
 Approximating  $u_{\mathbf{x}_0}(\mathbf{y}) := u(\mathbf{x}_0, \mathbf{y})$  for a given  $\mathbf{x}_0 \in \mathcal{D}$ .
- ▶ Up to now:

$$u_{\mathbf{x}_0}(\mathbf{y}) \approx u_{\mathbf{x}_0}^{\text{sFFT}}(\mathbf{y}) := \sum_{\mathbf{k} \in \mathbf{I}_{\mathbf{x}_0}} c_{\mathbf{k}}^{\text{sFFT}}(u_{\mathbf{x}_0}) e^{2\pi i \mathbf{k} \cdot \mathbf{y}}$$

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- ▶ Need  $G$  calls of the sFFT to compute  $\mathbf{I}_{\mathbf{x}_g}$  and  $c_{\mathbf{k}}^{\text{sFFT}}(u_{\mathbf{x}_g})$ ,  $g = 1, \dots, G$ .

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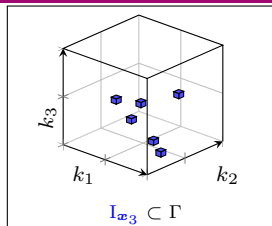
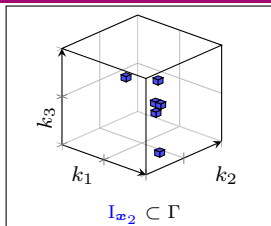
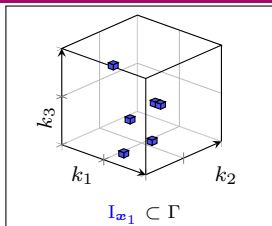
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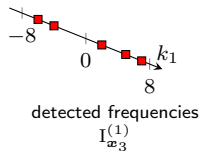
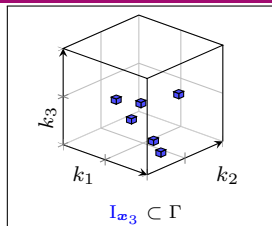
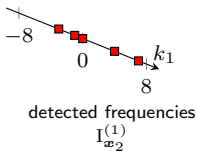
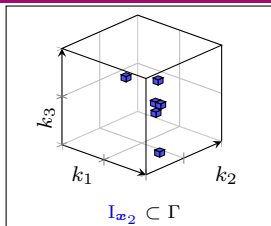
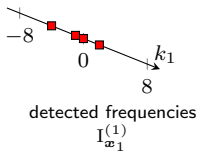
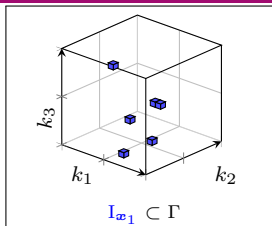
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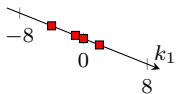
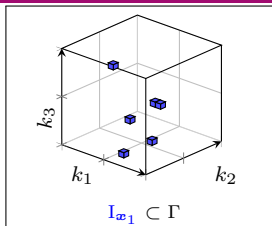
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- ▶ Solution: the *uniform* sFFT!

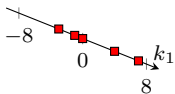
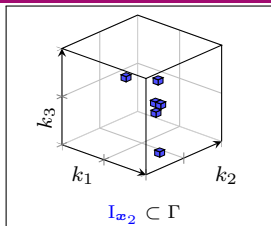




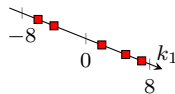
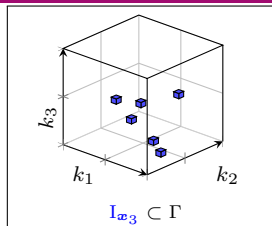




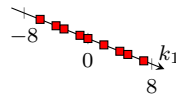
$$I_{\omega_1}^{(1)}$$



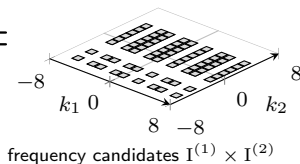
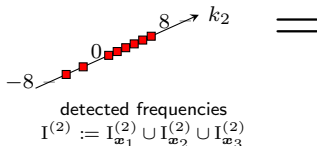
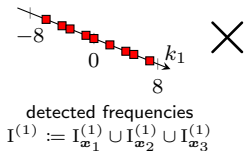
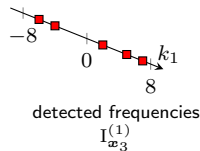
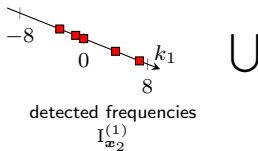
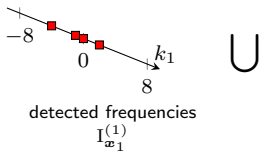
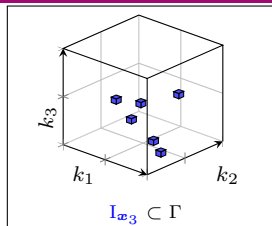
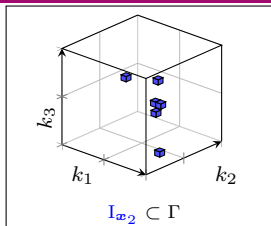
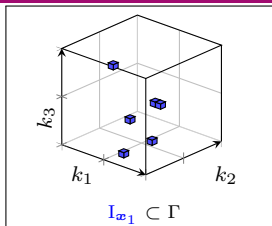
$$I_{\omega_2}^{(1)}$$

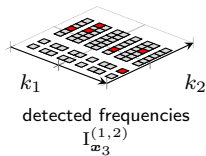
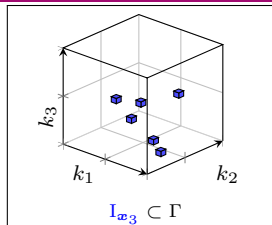
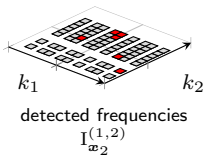
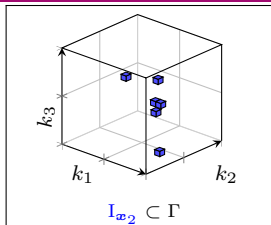
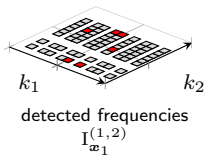
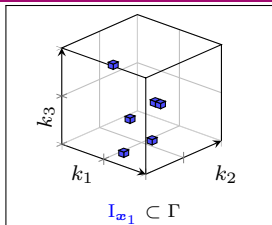


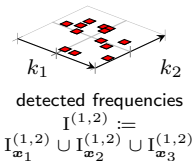
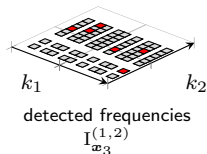
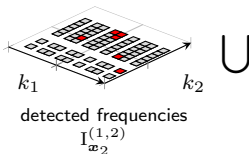
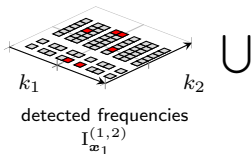
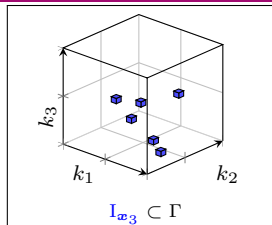
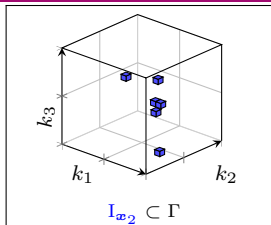
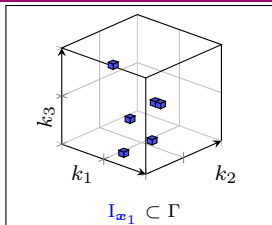
$$I_{\omega_3}^{(1)}$$

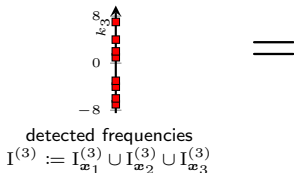
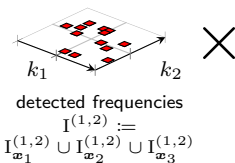
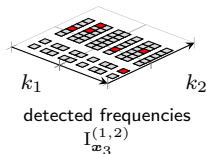
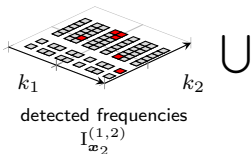
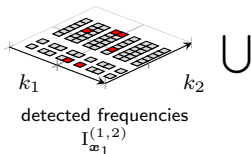
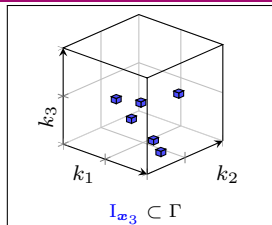
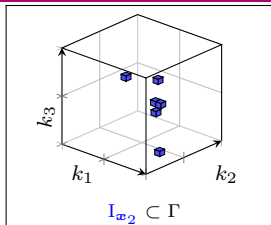
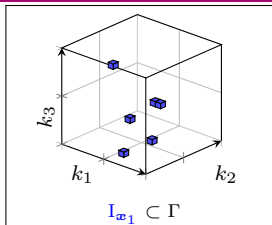


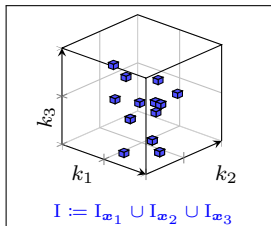
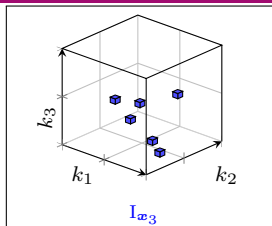
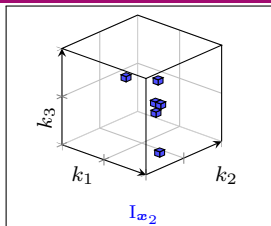
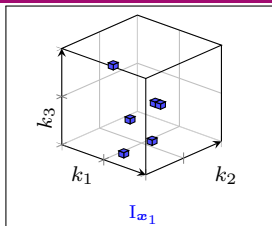
$$I^{(1)} := I_{\omega_1}^{(1)} \cup I_{\omega_2}^{(1)} \cup I_{\omega_3}^{(1)}$$











► Result:

$$u_{x_g}(\mathbf{y}) \approx u_{x_g}^{\text{usFFT}}(\mathbf{y}) := \sum_{\mathbf{k} \in I} c_{\mathbf{k}}^{\text{usFFT}}(u_{x_g}) e^{2\pi i \mathbf{k} \cdot \mathbf{y}} \quad g = 1, \dots, G$$

► Output:

- index set  $I \in \Gamma$  with  $I_{x_g} \subset I$  for all  $g = 1, \dots, G$
- approximations  $c_{\mathbf{k}}^{\text{usFFT}}(u_{x_g}), \mathbf{k} \in I$ , for all  $g = 1, \dots, G$



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- approximations  $c_{\mathbf{k}}^{\text{usFFT}}(u_{x_g}), \mathbf{k} \in I$ , for all  $g = 1, \dots, G$

► samples  $\hat{=}$  amount of PDE solutions needed:

$$\mathcal{O} \left( d s \max(s, N_\Gamma) \log^2 \frac{d s G N_\Gamma}{\delta} + \max(s G, N_\Gamma) \log \frac{d s G}{\delta} \right)$$

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► computational complexity of the usFFT:

$$\mathcal{O}\left(d^2 s^2 G^2 N_{\Gamma} \log^3 \frac{d s G N_{\Gamma}}{\delta}\right)$$

with high probability  $1 - \delta$

$$\mathcal{O}\left(d^2 s^3 G^2 N_{\Gamma} \log^3 \frac{d s G N_{\Gamma}}{\delta}\right)$$

worst case

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- approximations  $c_{\mathbf{k}}^{\text{usFFT}}(u_{x_g}), \mathbf{k} \in I$ , for all  $g = 1, \dots, G$

- samples  $\hat{=}$  amount of PDE solutions needed:  $G \lesssim ds$

$$\mathcal{O}\left(ds \max(s, N_\Gamma) \log^2 \frac{dsG N_\Gamma}{\delta} + \max(sG, N_\Gamma) \log \frac{dsG}{\delta}\right)$$

- computational complexity of the usFFT:

$$\mathcal{O}\left(d^2 s^2 G^2 N_\Gamma \log^3 \frac{dsG N_\Gamma}{\delta}\right)$$

with high probability  $1 - \delta$

$$\mathcal{O}\left(d^2 s^3 G^2 N_\Gamma \log^3 \frac{dsG N_\Gamma}{\delta}\right)$$

worst case

Consider the problem

$$\begin{aligned}
 -\nabla_{\mathbf{x}} \cdot (a(\mathbf{x}, \mathbf{y}) \nabla_{\mathbf{x}} u(\mathbf{x}, \mathbf{y})) &= 1 & \mathbf{x} \in D, \mathbf{y} \in D_{\mathbf{y}} \\
 u(\mathbf{x}, \mathbf{y}) &= 0 & \forall \mathbf{x} \in \partial D, \mathbf{y} \in D_{\mathbf{y}}
 \end{aligned}$$

with  $D = (0, 1)^2$ ,  $D_{\mathbf{y}} = [-1, 1]^{20}$ ,  $\mathbf{y} \sim \mathcal{U}([-1, 1]^{20})$  and the random coefficient

$$a(\mathbf{x}, \mathbf{y}) = 1 + \sum_{j=1}^{20} y_j \psi_j(\mathbf{x})$$

with

$$\psi_j(\mathbf{x}) := \frac{0.9}{\zeta(2)} j^{-2} \cos(2\pi m_1(j)x_1) \cos(2\pi m_2(j)x_2), \quad \mathbf{x} \in D, j \geq 1.$$

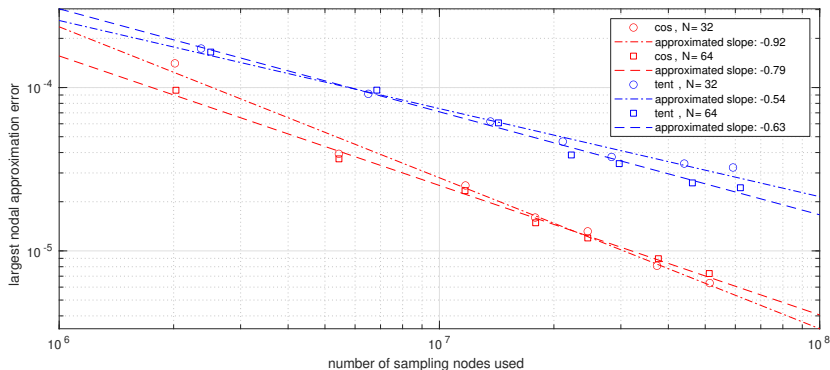
$j$	1	2	3	4	5	6	7	8	9	10	11	12	13	14	...
$m_1(j)$	0	1	0	1	2	0	1	2	3	0	1	2	3	4	...
$m_2(j)$	1	0	2	1	0	3	2	1	0	4	3	2	1	0	...

Example taken from

M. Eigel, C. J. Gittelsohn, C. Schwab and E. Zander.

*Adaptive stochastic Galerkin FEM.*

Comput. Methods Appl. Mech. Engrg., 270: 247–269, 2014.



**Figure:** Largest error  $\text{err}_2^\eta$  w.r.t. the nodes  $\mathbf{x}_g$  for different parameter settings, i.e.,  $s = 100, 250, 500, 750, 1000, 1500, 2000$ , for the affine example.

$$\text{err}_2^\eta(\mathbf{x}_g) := \sqrt{\frac{1}{n_{\text{test}}} \sum_{j=1}^{n_{\text{test}}} |\tilde{u}(\mathbf{x}_g, \mathbf{y}^{(j)}) - u^{\text{usFFT}}(\mathbf{x}_g, \mathbf{y}^{(j)})|^2}$$

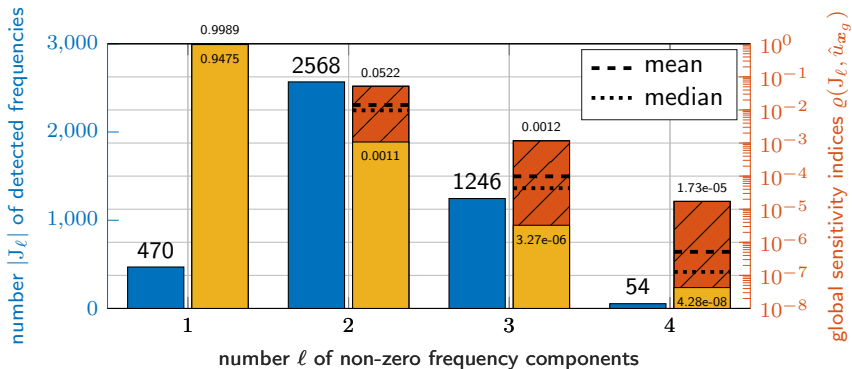


Figure: Analysis of the approximation for the affine example with  $s = 2000$ ,  $N = 32$ .

$$\varrho(J, \tilde{u}_{x_g}^{\text{usFFT}}) := \frac{\sigma^2(\tilde{u}_{x_g, J}^{\text{usFFT}})}{\sigma^2(\tilde{u}_{x_g}^{\text{usFFT}})} = \frac{\sum_{\mathbf{k} \in J \setminus \{\mathbf{0}\}} |c_{\mathbf{k}}^{\text{usFFT}}(\tilde{u}_{x_g})|^2}{\sum_{\mathbf{k} \in I \setminus \{\mathbf{0}\}} |c_{\mathbf{k}}^{\text{usFFT}}(\tilde{u}_{x_g})|^2} \in [0, 1],$$

Consider the problem

$$\begin{aligned}
 -\nabla_{\mathbf{x}} \cdot (a(\mathbf{x}, \mathbf{y}) \nabla_{\mathbf{x}} u(\mathbf{x}, \mathbf{y})) &= f(\mathbf{x}) & \mathbf{x} \in D, \mathbf{y} \in D_{\mathbf{y}} \\
 u(\mathbf{x}, \mathbf{y}) &= 0 & \forall \mathbf{x} \in \partial D, \mathbf{y} \in D_{\mathbf{y}}
 \end{aligned}$$

with  $f(\mathbf{x}) = \sin(1.3\pi x_1 + 3.4\pi x_2) \cos(4.3\pi x_1 - 3.1\pi x_2)$ ,  $D = (0, 1)^2$ ,  $D_{\mathbf{y}} = \mathbb{R}^{10}$ ,  $\mathbf{y} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$  and the random coefficient

$$\log a(\mathbf{x}, \mathbf{y}) = \sum_{j=1}^{10} \frac{y_j}{j} \sin(2\pi j x_1) \cos(2\pi(11-j)x_2).$$

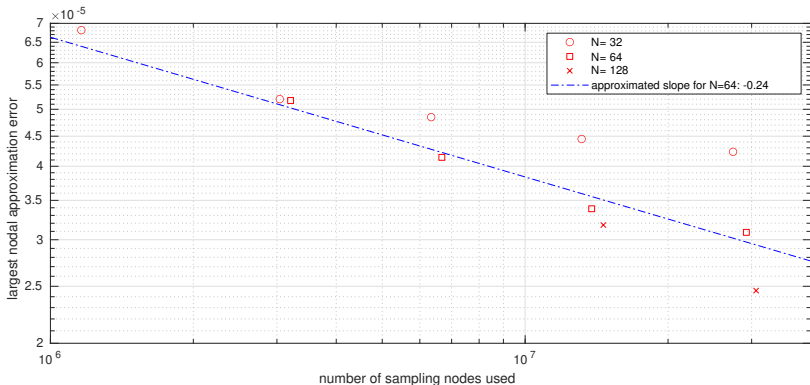
Example taken and modified from

M. Cheng, T. Y. Hou, M. Yan and Z. Zhang.

*A data-driven stochastic method for elliptic PDEs with random coefficients.*

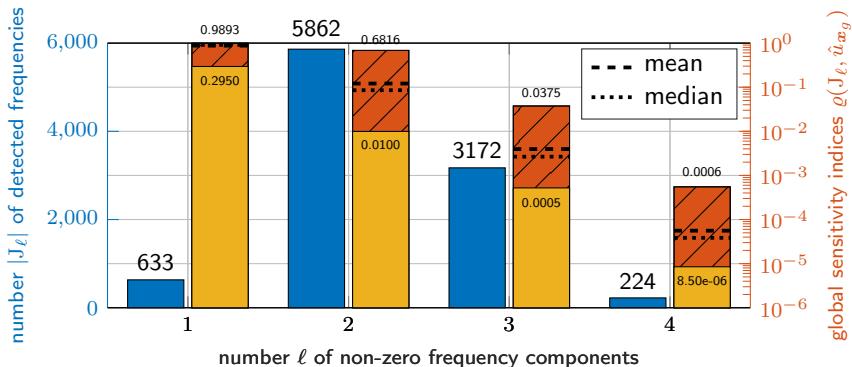
SIAM/ASA J. Uncertain. Quantif., 1: 452-493, 2013.





**Figure:** Largest error  $\text{err}_2^\eta$  w.r.t. the nodes  $\mathbf{x}_g$  for different parameter settings, i.e.,  $s = 100, 250, 500, 1000, 2000$ , for the lognormal example.

$$\text{err}_2^\eta(\mathbf{x}_g) := \sqrt{\frac{1}{n_{\text{test}}} \sum_{j=1}^{n_{\text{test}}} |\tilde{u}(\mathbf{x}_g, \mathbf{y}^{(j)}) - u^{\text{usFFT}}(\mathbf{x}_g, \mathbf{y}^{(j)})|^2}$$



**Figure:** Analysis of the approximation for the lognormal example with  $s = 2000$ ,  $N = 32$ .

$$\varrho(J, \tilde{u}_{x_g}^{\text{usFFT}}) := \frac{\sigma^2(\tilde{u}_{x_g, J}^{\text{usFFT}})}{\sigma^2(\tilde{u}_{x_g}^{\text{usFFT}})} = \frac{\sum_{k \in J \setminus \{0\}} |c_k^{\text{usFFT}}(\tilde{u}_{x_g})|^2}{\sum_{k \in I \setminus \{0\}} |c_k^{\text{usFFT}}(\tilde{u}_{x_g})|^2} \in [0, 1],$$

- ▶ Main advantages of the usFFT:
  - ▶ fully adaptive, no critical a priori choice needed
  - ▶ sample efficient (in terms of sampling locations)
  - ▶ approximation gives insight on the influence and interactions of the  $y_j$
  - ▶ adapts easily to other domains, boundary conditions, ...
  - ▶ non-intrusive and parallelizable

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- ▶ Lutz Kämmerer, Daniel Potts, Fabian Taubert  
*The uniform sparse FFT with application to PDEs with random coefficients*  
ArXiv e-prints, 2021. arXiv:2109.04131 [math.NA]
  
- ▶ Thank you for your attention!