

$$g(x)v(x) - \frac{1}{\pi} \int_{-1}^1 \frac{v'(t)}{t-x} dt + \frac{1}{\pi} \int_{-1}^1 h(x,t)v(t) dt = f(x), \quad (1)$$

$$v(-1) = v(1) = 0. \quad (2)$$

For a function $v \in L^p(-1, 1)$ possessing a generalized derivative $v' \in L^p(-1, 1)$, we have

$$\frac{d}{dx} \int_{-1}^1 \frac{v(t)}{t-x} dt = \int_{-1}^1 \frac{v'(t)}{t-x} dt - \frac{v(-1)}{1+x} + \frac{v(1)}{1-x}, \quad x \in (-1, 1),$$

Eq. (1) together with (2) can be written in the form

$$g(x)v(x) - \frac{1}{\pi} \int_{-1}^1 \frac{v(t)}{(t-x)^2} dt + \frac{1}{\pi} \int_{-1}^1 h(x,t)v(t) dt = f(x), \quad -1 < x < 1 \quad (3)$$

where the hypersingular integral operator has to be understood in the sense of

$$\int_{-1}^1 \frac{v(t)}{(t-x)^2} dt = \frac{d}{dx} \int_{-1}^1 \frac{v(t)}{t-x} dt \quad (4)$$

Recall that for physical reason we look for a solution in the form

$$v(x) = \varphi(x)u(x), \quad \varphi(x) = \sqrt{1-x^2} \quad (5)$$

$$g(x)\varphi(x)u(x) - \frac{1}{\pi} \int_{-1}^1 \frac{\varphi(x)u(x)}{(t-x)^2} dt + \frac{1}{\pi} \int_{-1}^1 h(x,t)\varphi(x)u(x) dt = f(x), \quad (6)$$

where the hypersingular integral operator has to be understood in the sense of

$$\int_{-1}^1 \frac{\varphi(x)u(x)}{(t-x)^2} dt = \frac{d}{dx} \int_{-1}^1 \frac{\varphi(x)u(x)}{t-x} dt \quad (7)$$

Multiplication Operator

$$\Gamma(x) = g(x)\varphi(x), \quad (M_\Gamma)u(x) = \Gamma(x)u(x) \quad (8)$$

Cauchy Singular Integral Operator

$$(Su)(x) = -\frac{1}{\pi} \int_{-1}^1 \frac{u(t)}{t-x} \varphi(t) dt \quad (9)$$

Hypersingular Integral Operator

$$V = DS, \quad D = \frac{d}{dx}, \quad (10)$$

Kernel Integral Operator

$$(Hu)(x) = \frac{1}{\pi} \int_{-1}^1 h(x, t)u(t)\varphi(t)dt, \quad (11)$$

$$(M_{\Gamma} + V + H)u = f \quad (12)$$

► Collocation method

Let

$$v^{\gamma,\delta}(x) = (1-x)^\gamma(1+x)^\delta, \quad \gamma, \delta > -1$$

be a Jacobi weight and let $p_n^{\gamma,\delta}$ refer as the normalized Jacobi polynomial (with positive leading coefficient) of degree n with respect to the Jacobi weight $v^{\gamma,\delta}$. Moreover, let $x_{nk}^{\gamma,\delta}$ with $-1 < x_{nn}^{\gamma,\delta} < \dots < x_{n1}^{\gamma,\delta} < 1$ be the zeros of $p_n^{\gamma,\delta}$ and denote by $L_n^{\gamma,\delta}$ the Lagrange interpolation operator

$$L_n^{\gamma,\delta} f = \sum_{k=1}^n f(x_{nk}^{\gamma,\delta}) l_{nk}^{\gamma,\delta}, \quad l_{nk}^{\gamma,\delta}(x) = \prod_{j=1, j \neq k}^n \frac{x - x_{nj}^{\gamma,\delta}}{x_{nk}^{\gamma,\delta} - x_{nj}^{\gamma,\delta}}.$$

Since we look for a solution of our hypersingular integral equation of the form $u(x)\varphi(x) = u(x)\sqrt{1-x^2}$, this suggest us to choose $\gamma = \delta = \frac{1}{2}$, then p_n^φ is the n -th orthonormal Tchebychev polynomial of the second kind

$p_n^\varphi = \sqrt{2}U_n$ where $U_n(x) = \frac{\sin[(n+1)\xi]}{\sin \xi}$ and the zeros have the following expressions

$$x_{nk}^\varphi = \cos \frac{k\pi}{n+1}, \quad k = 1, \dots, n.$$

The collocation method consists looking for an approximate solution $u_n \in P_{n-1}$ of equation (12) and solving the linear system

$$[(M_\Gamma + V + H)u_n](x_{nk}^\varphi) = f(x_{nk}^\varphi), \quad k = 1, \dots, n,$$

or (that is the same) to solve the equation

$$L_n^\varphi(M_\Gamma + V + H)u_n = L_n^\varphi f.$$

Now, we remember that for each $s \geq 0$, the hypersingular integral operator

$V = DS \in \mathcal{L}(L_\varphi^{2,s+1}, L_\varphi^{2,s})$ is a continuous isomorphism and

$$Vu = DSu = \sum_{n=0}^{\infty} (n+1) \langle u, p_n^\varphi \rangle_\varphi p_n^\varphi. \quad (13)$$

By this, we deduce that the operator V transforms polynomials into polynomials i.e.

$$L_n^\varphi V u_n = V u_n$$

Then, the previous equation is equivalent to

$$[V + L_n^\varphi (M_\Gamma + H)] u_n = L_n^\varphi f. \quad (14)$$

Theorem 1. *Assume that*

- $s > 1/2$;
- $f \in L_{\varphi}^{2,s}$;
- For $f \equiv 0$ equation (12) has only the trivial solution $u \equiv 0$ in $L_{\varphi}^{2,1}$;
- $\Gamma \in C_{\varphi}^r$ for some integer r , $0 \leq s \leq r$;
- $h(., t) \in L_{\varphi}^{2,s}$ uniformly w.r.t. $t \in [-1, 1]$.

Then, for all sufficiently large n , the approximate equation (14) is uniquely solvable, and the solution u_n^ converges to the unique solution u^* of*

hypersingular integral equation (12) in the norm of $L_{\varphi}^{2,s+1}$. Moreover, for $0 \leq t \leq s$,

$$\|u_n^* - u^*\|_{\varphi,t+1} \leq \text{const } n^{t-s} \|u^*\|_{\varphi,s+1}.$$

► **Quadrature method (discrete collocation method)**

We consider the operator H and we approximate this with the following gaussian quadrature rule with respect to the variable t

$$\begin{aligned} (Hu)(x) &= \frac{1}{\pi} \int_{-1}^1 h(x,t)u(t)\varphi(t) dt \approx \\ &\approx (H_n u)(x) = \sum_{k=1}^n \lambda_{nk}^{\varphi} h(x, x_{nk}^{\varphi})u(x_{nk}^{\varphi}), \end{aligned}$$

where

$$x_{nk}^\varphi = \cos \frac{k\pi}{n+1},$$

$$\lambda_{nk}^\varphi = \frac{1 - (x_{nk}^\varphi)^2}{n+1} = \frac{1}{n+1} \sin^2 \frac{k\pi}{n+1}, \quad k = 1, \dots, n.$$

The quadrature or discrete collocation method consists in solving the equation

$$V + L_n^\varphi(M_\Gamma + H_n)u_n = L_n^\varphi f.$$

The solution of this equation again belongs to \mathbb{P}_{n-1} . Since, for such u_n , we have

$$\begin{aligned} (H_n u_n)(x) &= \sum_{k=1}^n \lambda_{nk}^\varphi h(x, x_{nk}^\varphi) u_n(x_{nk}^\varphi) \\ &= \frac{1}{\pi} \int_{-1}^1 u_n(t) L_{nt}^\varphi[h(x, t)] \varphi(t) dt =: (\widehat{H}_n u_n)(x), \end{aligned} \quad (15)$$

the approximate equation is equivalent to

$$V + L_n^\varphi(M_\Gamma + \widehat{H}_n)u_n = L_n^\varphi f.$$

The following Lemma is crucial for proving the convergence of both the discrete collocation method and the fast algorithm we now present.

Lemma 1. *Assume $h(x, \cdot) \in L_\varphi^{2,s}$ for some $s > 1/2$ uniformly w.r.t. $x \in [-1, 1]$. Then, for $0 \leq t \leq s$ and $u \in L_\varphi^2$,*

$$\|L_m^{\gamma,\delta}(\widehat{H}_n - H)u\|_{\gamma,\delta,t} \leq \text{const} m^t n^{-s} \|u\|_\varphi.$$

► A Fast Algorithm

Now we show as we can construct a fast algorithm to solve numerically the simple hypersingular integral equation

$$\gamma_0 u(x) - \frac{1}{\pi} \int_{-1}^1 \frac{u(t)}{(t-x)^2} \varphi(t) dt + \frac{1}{\pi} \int_{-1}^1 h(x,t) u(t) \varphi(t) dt = f(x),$$

or in the operator form

$$M_{\gamma_0} + V + H = f. \quad (16)$$

This technique can be used also for the more general equation

$$\gamma_0 u(x) - \frac{1}{\pi} \int_{-1}^1 \frac{u(t)}{(t-x)^2} \varphi(t) dt +$$

$$+\frac{1}{\pi} \int_{-1}^1 [h(x, t) - \gamma_1 \ln |x - t|] u(t) \varphi(t) dt = f(x).$$

We approximate the operator $M_{\gamma_0} + V + H$ by using the quadrature method.

$$(M_{\gamma_0} + V + L_n^\varphi \widehat{H}_n) u_n = L_n^\varphi f,$$

where we recall that

$$(\widehat{H}_n u)(x) := \frac{1}{\pi} \int_{-1}^1 u(t) L_{nt}^\varphi [h(x, t)] \varphi(t) dt$$

We again remark that each solution u_n belongs to \mathbb{P}_{n-1} , such that

$$(\widehat{H}_n u_n)(x) = \sum_{k=1}^n \lambda_{nk}^\varphi h(x, x_{nk}^\varphi) u_n(x_{nk}^\varphi).$$

We recall that, since $\alpha = \beta = \frac{1}{2}$, the n -th orthonormal Tchebychev polynomial of the second kind $p_n^\varphi = \sqrt{2}U_n$ where $U_n(x) = \frac{\sin[(n+1)\xi]}{\sin \xi}$ and the zeros and the weights have the following expressions

$$x_{nk}^\varphi = \cos \frac{k\pi}{n+1},$$

$$\lambda_{nk}^\varphi = \frac{1 - (x_{nk}^\varphi)^2}{n+1} = \frac{1}{n+1} \sin^2 \frac{k\pi}{n+1}, \quad k = 1, \dots, n.$$

We use the following representation for the fundamental Lagrange polynomials (recalling that $l_{nk}^\varphi(x_{nj}^\varphi) = \delta_{jk}$, $j, k = 1, \dots, n$ and δ_{jk} is the Kronecher symbol)

$$l_{nk}^\varphi(x) = \lambda_{nk}^\varphi \sum_{j=0}^{n-1} p_j^\varphi(x_{nk}^\varphi) p_j^\varphi(x)$$

$$l_{nk}^{\varphi}(x) = \sum_{j=0}^{n-1} c_j^{\varphi} p_j^{\varphi}(x)$$

$$c_j^{\varphi} = \int_{-1}^1 l_{nk}^{\varphi}(x) p_j^{\varphi}(x) \varphi(x) dx = \sum_{r=1}^n \lambda_{nr}^{\varphi} l_{nk}^{\varphi}(x_{nr}^{\varphi}) p_j^{\varphi}(x_{nr}^{\varphi}) = \lambda_{nk}^{\varphi} p_j^{\varphi}(x_{nk}^{\varphi})$$

We seek the approximate solution u_n in the form

$$u_n(x) = \sum_{k=1}^n \xi_{nk} l_{nk}^{\varphi}(x), \quad u_n(x_{nk}^{\varphi}) = \xi_{nk}$$

where ξ_{nk} are n unknown. Therefore we need to solve the linear system and to do this we choose as collocation points the zeros of the n -th Tchebychev polynomial x_{nr}^{φ} , $r = 1, \dots, n$.

$$(M_{\gamma_0} + V + \widehat{H}_n) u_n(x_{nr}^{\varphi}) = f(x_{nr}^{\varphi}), \quad r = 1, \dots, n$$

Recalling that

$$(\widehat{H}_n u_n)(x) = \sum_{k=1}^n \lambda_{nk}^\varphi h(x, x_{nk}^\varphi) u_n(x_{nk}^\varphi),$$

and using Lemma 9

$$(V l_{nk}^\varphi)(x) = \lambda_{nk}^\varphi \sum_{j=0}^{n-1} p_j^\varphi(x_{nk}^\varphi) (j+1) p_j^\varphi(x),$$

we obtain

$$(M_{\gamma_0} u_n)(x_{nr}^\varphi) = \gamma_0 \sum_{k=1}^n \xi_{nk} l_{nk}^\varphi(x_{nr}^\varphi) = \gamma_0 \xi_{nr}$$

$$\begin{aligned}
(Vu_n)(x_{nr}^\varphi) &= \sum_{k=1}^n \xi_{nk} (Vl_{nk}^\varphi)(x_{nr}^\varphi) = \\
&= \sum_{k=1}^n \xi_{nk} \lambda_{nk}^\varphi \sum_{j=0}^{n-1} p_j^\varphi(x_{nk}^\varphi) (j+1) p_j^\varphi(x_{nr}^\varphi) \\
(\widehat{H}_n u_n)(x_{nr}^\varphi) &= \sum_{k=1}^n \lambda_{nk}^\varphi \xi_{nk} h(x_{nr}^\varphi, x_{nk}^\varphi).
\end{aligned}$$

Denoting by

$$\xi_n = [\xi_{nk}]_{k=1}^n, \quad \eta_n = [f(x_{nj}^\varphi)]_{j=1}^n,$$

$$\mathbf{I}_n = [\delta_{jk}]_{j,k=1}^n, \quad \mathbf{D}_n = \text{diag}[1, \dots, n], \quad \Lambda_n = \text{diag}[\lambda_{n1}^\varphi, \dots, \lambda_{nn}^\varphi]$$

$$\mathbf{U}_n = [p_j^\varphi(x_{nk}^\varphi)]_{j=0, k=1}^{n-1, n}$$

$$\mathbf{V}_n = \mathbf{U}_n^T \mathbf{D}_n \mathbf{U}_n, \quad \mathbf{H}_n = [h(x_{nj}^\varphi, x_{nk}^\varphi)]_{j,k=1}^n,$$

then, we can write the system in the vectorial form

$$(\gamma_0 \mathbf{I}_n + \mathbf{V}_n \Lambda_n + \mathbf{H}_n \Lambda_n) \boldsymbol{\xi}_n = \boldsymbol{\eta}_n$$

From $\delta_{jk} = \langle p_k^\varphi, p_j^\varphi \rangle_\varphi = \sum_{l=1}^n \lambda_{nl}^\varphi p_k^\varphi(x_{nl}^\varphi) p_j^\varphi(x_{nl}^\varphi)$ it follows

$$\mathbf{I}_n = \mathbf{U}_n \Lambda_n \mathbf{U}_n^T.$$

We assume that the vector $\boldsymbol{\eta}_n$ of the values of the function f at the collocation points x_{nj}^φ , $j = 1, \dots, n$, as well as the values $h(x_{nj}^\varphi, x_{nk}^\varphi)$, $j, k = 1, \dots, n$, are given.

Choose an integer $0 < m < n$ and write

$$u_n = \sum_{k=0}^{m-1} \alpha_k p_k^\varphi + \sum_{k=m}^{n-1} \alpha_k p_k^\varphi = \mathcal{P}_m u_n + \mathcal{Q}_m u_n,$$

where

$$\mathcal{P}_m u = \sum_{k=0}^{m-1} \langle u, p_k^\varphi \rangle_\varphi p_k^\varphi \quad \text{and} \quad \mathcal{Q}_m = I - \mathcal{P}_m.$$

Set $\alpha_k = \langle v_n^*, p_k^\varphi \rangle_\varphi$, $k = m, \dots, n-1$, where $v_n^* = \sum_{k=0}^{n-1} \beta_{nk}^* p_k^\varphi$ is the solution of

$$(M_{\gamma_0} + V)v_n = L_n^\varphi f. \quad (17)$$

At first we note that for the case of $h \equiv 0$, Theorem 1 shows that this equation (17) is uniquely solvable for all sufficiently large n , if for $f \equiv 0$

equation has only the trivial solution $u \equiv 0$ in $L_{\varphi}^{2,1}$.

For $\beta_n = [\beta_{nk}]_{k=0}^{n-1}$ we have

$$\left[(M_{\gamma_0} v_n)(x_{nj}^{\varphi}) \right]_{j=1}^n = \left[\gamma_0 \sum_{k=0}^{n-1} \beta_{nk} p_k^{\varphi}(x_{nj}^{\varphi}) \right]_{j=1}^n = \gamma_0 \mathbf{U}_n^T \beta_n,$$

and

$$\left[(V v_n)(x_{nj}^{\varphi}) \right]_{j=1}^n = \left[\sum_{k=0}^{n-1} \beta_{nk} (k+1) p_k^{\varphi}(x_{nj}^{\varphi}) \right]_{j=1}^n = \mathbf{U}_n^T \mathbf{D}_n \beta_n.$$

So we can write equation (17) in the form

$$\mathbf{U}_n^T (\gamma_0 \mathbf{I}_n + \mathbf{D}_n) \beta_n = \eta_n$$

Recalling that $\mathbf{I}_n = \mathbf{U}_n \mathbf{\Lambda}_n \mathbf{U}_n^T$, we can write also (17) in this way

$$(\gamma_0 \mathbf{I}_n + \mathbf{D}_n) \boldsymbol{\beta}_n = \mathbf{U}_n \mathbf{\Lambda}_n \boldsymbol{\eta}_n.$$

Since the transform

$$\mathbf{U}_n \mathbf{\Lambda}_n = \frac{\sqrt{2}}{n+1} \left[\sin \frac{jk\pi}{n+1} \right]_{j,k=1}^n \text{diag} \left[\sin \frac{k\pi}{n+1} \right]_{k=1}^n$$

can be applied to a vector with $O(n \ln n)$ computational complexity, we can compute $\boldsymbol{\beta}_n$ (and so $\alpha_m, \dots, \alpha_{n-1}$) with

$O(n \ln n)$ -complexity

taking into account the simple structure of the matrix on the left hand side of $(\gamma_0 \mathbf{I}_n + \mathbf{D}_n) \boldsymbol{\beta}_n = \mathbf{U}_n \mathbf{\Lambda}_n \boldsymbol{\eta}_n$.

The second step of our algorithm consists in setting $\mathcal{P}_m u_n = w_m^*$, where w_m^* is the solution of

$$\left(M_{\gamma_0} + V + L_m^\varphi \widehat{H}_m \right) w_m = L_m^\varphi \left(f - (M_{\gamma_0} + V) \mathcal{Q}_m v_n^* \right). \quad (18)$$

This equation is equivalent to

$$\left[\mathbf{U}_m^T (\gamma_0 \mathbf{I}_m + \mathbf{D}_m) \mathbf{U}_m + \mathbf{H}_m \right] \Lambda_m \omega_m = \tilde{\eta}_m,$$

with $\omega_m = [w_m(x_{mk}^\varphi)]_{k=1}^m$ and

$$\tilde{\eta}_m = [f(x_{mj}^\varphi) - ((M_{\gamma_0} + V) \mathcal{Q}_m v_n^*)(x_{mj}^\varphi)]_{j=1}^m.$$

The matrix \mathbf{U}_m can be generated with $O(m^2)$ -complexity using the three term recurrence relation of the orthogonal polynomials $p_j^\varphi(x)$. Thus this equation can be solved with $O(m^3)$ -complexity.

The values $f(x_{mj}^\varphi)$ are already been given if we choose m in such a way that $\frac{n+1}{m+1}$ is an integer, which implies $x_{mj}^\varphi \in \{x_{nk}^\varphi : k = 1, \dots, n\}$ for $j = 1, \dots, m$.

So, it remains to compute $U_n^T(\gamma_0 \mathbf{I}_n + \mathbf{D}_n)\tilde{\beta}_n$, where

$$\tilde{\beta}_n = [0, \dots, 0, \beta_{nm}, \dots, \beta_{n,n-1}]^T.$$

This can be done with $O(n \ln n)$ operations taking into account that

$$U_n^T = \sqrt{2} \operatorname{diag} \left[\sin^{-1} \frac{k\pi}{n+1} \right]_{k=1}^n \left[\sin \frac{jk\pi}{n+1} \right]_{k,j=1}^n$$

can again be handled as fast discrete sine transform.

The determination of the Fourier coefficients α_{nk} , $k = 0, \dots, m-1$, needs $O(m \ln m)$ operations, since $[\alpha_{nk}]_{k=0}^{m-1} = U_m \Lambda_m \omega_m$.

The computation of the Fourier coefficients of $u_n = w_m^* + \mathcal{Q}_m v_n^*$, can be done with $O(m^3 + n \ln n)$ numerical complexity.

Now, we make the following assumptions. For some $s > 1/2$

- 1) For $f \equiv 0$ equation (21) possesses in $L_\varphi^{s,1}$ only the trivial solution $u \equiv 0$. The same is assumed for the equation $(M_{\gamma_0} + V)u = 0$.
- 2) $h(., t) \in L_\varphi^{2,s+\delta}$ uniformly w.r.t. $t \in [-1, 1]$ and
- 3) $h(x, .) \in L_\varphi^{2,s+\delta}$ uniformly w.r.t. $x \in [-1, 1]$ for some $\delta \geq 0$.
- 4) The right hand side f of equation (21) belongs to $L_\varphi^{2,s}$.

Then, we can summarize our results with the

Theorem 2. [C., Criscuolo, Junghanns] Let $s > 1/2$, and m, n , $0 < m < n$, be integers such that $\frac{n+1}{m+1}$ is an integer and $c_1 n \leq m^3 \leq c_2 n$ with some positive constants c_1 and c_2 . Then, if the assumptions 1),2),3),4) are verified, for all sufficiently large m , equations (17) and (18) are uniquely solvable and $\tilde{u}_n^* = w_m^* + \mathcal{Q}_m v_n^*$ converges in the norm of $L_\varphi^{2,t+1}$, $0 \leq t < s$, to the unique solution $u^* \in L_\varphi^{2,s+1}$ of equation (16), where, for $\max\{\frac{1}{2}, s - \frac{\delta}{2}\} < t \leq s$,

$$\|\tilde{u}_n^* - u^*\|_{\varphi,t+1} \leq \text{const} n^{t-s} \|u^*\|_{\varphi,s+1}.$$

Moreover, the solution of (17) and (18) needs $O(n \ln n)$ operations.

► Numerical Examples

We apply the fast algorithm to the following hypersingular integral equations 1.

$$u(x) - \frac{1}{\pi} \int_{-1}^1 \frac{u(t)}{(t-x)^2} \varphi(t) dt + \frac{1}{\pi} \int_{-1}^1 (|x| + |t|) u(t) \varphi(t) dt =$$
$$= 2 + \frac{|x|}{2} + \frac{2}{3\pi}; \quad u(x) \equiv 1, \quad h(., t), h(x, .), f \in L^2_{\varphi, \frac{3}{2}-\epsilon}, \quad \epsilon > 0.$$

The assumptions of Theorem 2 are satisfied, for example, for $s = 0.8$ and $\delta = 0.6$. Therefore, we can expect theoretically the convergence rate

$$\|u_n^* - u^*\|_{\varphi, t+1} \leq \text{const} n^{t-0.8} \|u^*\|_{\varphi, 1.8}, \quad 0.5 < t \leq 0.8.$$

Example 1.		
n	m	$\ u_n^* - u^*\ _{\varphi, 1.51}$
8	2	0.123D-00
27	3	0.801D-01
64	4	0.562D-01
125	5	0.519D-01
216	6	0.386D-01
343	7	0.393D-01
399	15	0.205D-01

2.

$$\begin{aligned}
 u(x) &= \frac{1}{\pi} \int_{-1}^1 \frac{u(t)}{(t-x)^2} \varphi(t) dt + \frac{1}{\pi} \int_{-1}^1 [t(x^2|x| + t|t|)] u(t) \varphi(t) dt = \\
 &= x \left[\left(1 + \frac{4x}{15\pi} \right) |x| + \frac{6}{\pi} + \frac{3x^2 - 2}{\pi \sqrt{1-x^2}} \ln \frac{1 + \sqrt{1-x^2}}{1 - \sqrt{1-x^2}} \right],
 \end{aligned}$$

$$u(x) = x|x|, \quad h(., t), h(x, .) \in L^2_{\varphi, \frac{7}{2}-\epsilon}, f \in L^2_{\varphi, \frac{3}{2}-\epsilon} \quad \epsilon > 0.$$

The assumptions of Theorem 2 are satisfied, for example, for $s = 1.5 - \epsilon$ and $\delta = 2$. Therefore, we can expect theoretically the convergence rate, for $s < 1.5$,

$$\|u_n^* - u^*\|_{\varphi, t+1} \leq \text{const} n^{t-s} \|u^*\|_{\varphi, s+1}, \quad 0.5 < t \leq s.$$

Example 2.			
n	m	$\ u_n^* - \mathcal{P}_n u^*\ _{\varphi, 1.51}$	$\ u_n^* - \mathcal{P}_n u^*\ _{\varphi, 1.85}$
8	2	0.552D-01	0.107D-00
27	3	0.186D-01	0.520D-01
64	4	0.838D-02	0.283D-01
125	5	0.447D-02	0.212D-01
216	6	0.226D-02	0.125D-01
343	7	0.168D-02	0.112D-01
399	15	0.141D-02	0.102D-01

Finally, in the following two tables one can see the results obtained by means of the quadrature method.

Example 2 is more convenient than Example 1 for applying the fast algorithm, since already for small m in comparison with n the errors for the quadrature method and the fast algorithm are essentially the same. The reason for this is that in Example 2 the kernel $h(x, t)$ is really smoother

than the right hand side $f(x)$.

Example 1.	
n	$\ u_n^* - P_n u^*\ _{\varphi, 1.51}$
8	0.980D-03
27	0.199D-03
64	0.184D-04
125	0.980D-05
216	0.165D-05
343	0.131D-05
399	0.972D-06

Example 2.		
n	$\ u_n^* - \mathcal{P}_n u^*\ _{\varphi, 1.51}$	$\ u_n^* - \mathcal{P}_n u^*\ _{\varphi, 1.85}$
8	0.522D-01	0.107D-00
27	0.178D-01	0.511D-01
64	0.695D-02	0.271D-01
125	0.436D-02	0.211D-01
216	0.211D-02	0.124D-01
343	0.164D-02	0.112D-01
399	0.141D-02	0.102D-01