

A frame-theoretical approach to the inversion of the NFFT

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Mecklenburg Workshop
Approximation Methods and Fast Algorithms
Hasenwinkel, September 10-14, 2018

Overview

- 1 Introduction
- 2 Inversion of the NFFT
- 3 Frame-theoretical approach
- 4 Numerical Examples

Nonequispaced fast Fourier transform

Fast algorithm to evaluate a trigonometric polynomial

$$f(x) = \sum_{k=-\frac{M}{2}}^{\frac{M}{2}-1} \hat{f}_k e^{2\pi i k x}$$

at nonequispaced nodes $x_j \in [-\frac{1}{2}, \frac{1}{2})$, $j = 1, \dots, N$

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 [Potts, Steidl, Tasche 01]

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 sparse FFT diagonal

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- [Nieslony, Steidl 03]: Minimization of approximation error by

$$\text{Minimize}_{\mathbf{B} \in \mathbb{R}^{N \times \sigma M} : \mathbf{B} \text{ (} 2m+1 \text{)-sparse}} \|\mathbf{A} - \mathbf{BFD}\|_{\mathbb{F}}^2$$

iNFFT

Given: $f(x_j), j = 1, \dots, N$, for $f(x) = \sum_{k=-\frac{M}{2}}^{\frac{M}{2}-1} \hat{f}_k e^{2\pi i k x}$

Find: $\hat{f}_k \in \mathbb{C}, k = -\frac{M}{2}, \dots, \frac{M}{2} - 1$

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Motivation: FFT is invertible

various applications: MRI, solution of PDEs, ...

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Previous approaches:

- iterative methods: [Feichtinger, Gröchenig 95]: CG algorithm, $N > M$
[Kunis, Potts 07]: CG algorithm and NFFT, $N < M$
- direct method for $N = M$: [Dutt, Rokhlin 93]: Lagrange interpolation and FMM
[K. 17]: fast summation method
- frame-theoretical approach: [Gelb, Song 13/14],[Davis, Gelb, Song 16], $N > M$

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Now: new direct method for **general case** and **connection** to frame approach

Basic idea

Consider equispaced nodes

$$x_j = \frac{j}{N} \in \left[-\frac{1}{2}, \frac{1}{2}\right), j = -\frac{N}{2}, \dots, \frac{N}{2} - 1.$$

Obtain

$$\mathbf{A} = \left(e^{2\pi i k \frac{j}{N}} \right)_{j=-\frac{N}{2}, k=-\frac{M}{2}}^{\frac{N}{2}-1, \frac{M}{2}-1} \quad \text{and} \quad \mathbf{A}^* = \left(e^{-2\pi i k \frac{j}{N}} \right)_{k=-\frac{M}{2}, j=-\frac{N}{2}}^{\frac{M}{2}-1, \frac{N}{2}-1}.$$

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Consider matrix products:

$$\mathbf{A}^* \mathbf{A} = N \mathbf{I}_M \text{ for } N \geq M$$

$$\mathbf{A} \mathbf{A}^* = M \mathbf{I}_N \text{ for } N \leq M \text{ with } N \mid M$$

Basic idea

Consider **nonequispaced** nodes

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Obtain

$$\mathbf{A} = \left(e^{2\pi i k x_j} \right)_{j=-\frac{N}{2}, k=-\frac{M}{2}}^{\frac{N}{2}-1, \frac{M}{2}-1} \quad \text{and} \quad \mathbf{A}^* = \left(e^{-2\pi i k x_j} \right)_{k=-\frac{M}{2}, j=-\frac{N}{2}}^{\frac{M}{2}-1, \frac{N}{2}-1}.$$

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$$\mathbf{A} = \left(e^{2\pi i k x_j} \right)_{\substack{j=-\frac{N}{2}, \dots, \frac{N}{2}-1 \\ k=-\frac{M}{2}, \dots, \frac{M}{2}-1}} \quad \text{and} \quad \mathbf{A}^* = \left(e^{-2\pi i k x_j} \right)_{\substack{k=-\frac{M}{2}, \dots, \frac{M}{2}-1 \\ j=-\frac{N}{2}, \dots, \frac{N}{2}-1}}.$$

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Aim: $\mathbf{A} \mathbf{D}^* \mathbf{F}^* \mathbf{B}^* \approx M \mathbf{I}_N$
 ↙
 optimize

$$\rightsquigarrow \mathcal{O}(M \log M + N)$$

In these special cases an inversion is given.

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- ↪ preserve band structure and arithmetic complexity

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Problems:

(1) Solve

$$A\hat{f} = f,$$

given: f , find: \hat{f} . ⇒ inverse NFFT

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(2) Solve

$$A^*f = h,$$

given.: h , find.: f . ⇒ inverse adjoint NFFT

Inverse NFFT - underdetermined case

Assume

$$AD^*F^*B^* \approx MI_N$$

Inverse NFFT - underdetermined case

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$$AD^*F^*B^* \approx MI_N \iff \frac{1}{M} AD^*F^*B^* f \approx f \quad \forall f \in \mathbb{C}^N$$

Inverse NFFT - underdetermined case

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$$\begin{aligned}
 \mathbf{AD}^* \mathbf{F}^* \mathbf{B}^* \approx M \mathbf{I}_N &\iff \frac{1}{M} \mathbf{AD}^* \mathbf{F}^* \mathbf{B}^* \mathbf{f} \approx \mathbf{f} \quad \forall \mathbf{f} \in \mathbb{C}^N \\
 &\iff \mathbf{A} \tilde{\mathbf{f}} \approx \mathbf{f} \quad \forall \mathbf{f} \in \mathbb{C}^N
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\Rightarrow inverse NFFT as well as inverse adjoint NFFT

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$$\tilde{g}(x) = \sum_{j=1}^N f_j \tilde{w}_m(x_j - x)$$

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$$\|F D A^* B - I_{\sigma M}\|_F^2 = \sum_{l=-\frac{\sigma M}{2}}^{\frac{\sigma M}{2}-1} \|F D H_l b_l - e_l\|_2^2$$

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$$\rightsquigarrow \mathcal{O}(N^2 M^2 + N^3 M)$$

Frame-theoretical approach

Approach based on

[Gelb, Song 13] Approximating the inverse frame operator from localized frames

[Gelb, Song 14] A frame theoretic approach to the nonuniform fast Fourier transform

[Davis, Gelb, Song 16] A high-dimensional inverse frame operator approximation technique

⇒ connection to inverse NFFT

Definition

Let \mathcal{H} be a Hilbert space. A sequence $\{\varphi_j\}_{j=1}^{\infty} \subset \mathcal{H}$ is called **frame** if there exist $A, B > 0$ such that

$$A\|f\|^2 \leq \sum_{j=1}^{\infty} |\langle f, \varphi_j \rangle|^2 \leq B\|f\|^2 \quad \forall f \in \mathcal{H}.$$

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The operator

$$S: \mathcal{H} \rightarrow \mathcal{H}, \quad Sf = \sum_{j=1}^{\infty} \langle f, \varphi_j \rangle \varphi_j,$$

is named the **frame operator**.

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$$A\|f\|^2 \leq \sum_{j=1}^{\infty} |\langle f, \varphi_j \rangle|^2 \leq B\|f\|^2 \quad \forall f \in \mathcal{H}.$$

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⇒ goal: approximate S^{-1}

[Christensen 16]

Connection to iNFFT

Frame approximation:

$$\tilde{f} := \sum_{j=1}^N \sum_{l=-\frac{\sigma M}{2}}^{\frac{\sigma M}{2}-1} \langle f, \varphi_j \rangle p_{l,j} \psi_l,$$

with $\Phi^\dagger := [p_{l,j}]_{l=-\frac{\sigma M}{2}, j=1}^{\frac{\sigma M}{2}-1, N}$ Moore-Penrose pseudoinverse of

[Gelb, Song 13/14]

$$\Phi := [\langle \varphi_j, \psi_l \rangle]_{j=1, l=-\frac{\sigma M}{2}}^{N, \frac{\sigma M}{2}-1}$$

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\Rightarrow Look for approximation $\tilde{h}_k \approx \tilde{f}(k) \approx \hat{f}_k, \quad k = -\frac{M}{2}, \dots, \frac{M}{2} - 1.$

Connection to iNFFT

Choose

$$\{\varphi_j(k) := e^{-2\pi i k x_j}, j \in \mathbb{N}\} \quad \text{and} \quad \left\{ \psi_l(k) := \frac{e^{-2\pi i k l / \sigma M}}{\sigma M \hat{w}(-k)}, l \in \mathbb{Z} \right\}.$$

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Connection to INFFT

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with $\Phi^\dagger := [p_{l,j}]_{l=-\frac{\sigma M}{2}}^{\frac{\sigma M}{2}-1, j=1}^N$ Moore-Penrose pseudoinverse of

[Gelb, Song 13/14]

$$\Phi := [\langle \varphi_j, \psi_l \rangle]_{j=1, l=-\frac{\sigma M}{2}}^{N, \frac{\sigma M}{2}-1} = \left[\sum_{k=-\frac{M}{2}}^{\frac{M}{2}-1} \frac{1}{\sigma M \hat{w}(k)} e^{-2\pi i k (x_j - \frac{l}{\sigma M})} \right]_{j=1, l=-\frac{\sigma M}{2}}^{N, \frac{\sigma M}{2}-1}.$$

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Define

$$\tilde{\mathbf{h}} := (\tilde{h}_k)_{k=-\frac{M}{2}}^{\frac{M}{2}-1}, \quad \tilde{\mathbf{h}} := (\tilde{h}_k)_{k=-\frac{M}{2}}^{\frac{M}{2}-1} = (\tilde{f}(k))_{k=-\frac{M}{2}}^{\frac{M}{2}-1}.$$

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Theorem

For

$$\hat{\mathbf{w}} := \left(\frac{1}{\hat{w}(-k)} \right)_{k=-\frac{M}{2}}^{\frac{M}{2}-1}$$

with $\|\hat{\mathbf{w}}\|_2 < \infty$ the following estimates hold.

(i) For $\sigma M < N$ we have

$$\|\tilde{\mathbf{h}} - \tilde{\tilde{\mathbf{h}}}\|_2 \leq \frac{1}{\sqrt{\sigma M}} \|\hat{\mathbf{w}}\|_2 \|\Phi \mathbf{B}^* - \mathbf{I}_N\|_F \|\Phi^\dagger \mathbf{f}\|_2.$$

(ii) For $\sigma M > N$ we have

$$\|\tilde{\mathbf{h}} - \tilde{\tilde{\mathbf{h}}}\|_2 \leq \frac{1}{\sqrt{\sigma M}} \|\hat{\mathbf{w}}\|_2 \|\mathbf{B}^* \Phi - \mathbf{I}_{\sigma M}\|_F \|\Phi^\dagger \mathbf{f}\|_2.$$

Connection to iNFFT (II)

$$\Phi B^* = (BFDA^*)^T :$$

$$\begin{aligned} & \text{Minimize} && \|\Phi B^* - I_N\|_F^2 \\ & B \in \mathbb{R}^{N \times \sigma M} : B \text{ (} 2m+1 \text{)-sparse} \\ \\ \iff & \text{Minimize} && \|BFDA^* - I_N\|_F^2 \\ & B \in \mathbb{R}^{N \times \sigma M} : B \text{ (} 2m+1 \text{)-sparse} \end{aligned}$$

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\Rightarrow previously only optimization of D , new fast algorithms applicable

Inverse NFFT

Trigonometric function

$$f(x) = \cos^2(\pi x^2) \sin(10x^2), \quad x \in \left[-\frac{1}{2}, \frac{1}{2}\right)$$

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$$c_k(f) \approx \check{f}_k = \left(\frac{1}{M} \mathbf{D}^* \mathbf{F}^* \tilde{\mathbf{B}}^* \mathbf{f} \right)_k \quad \text{and} \quad c_k(f) \approx \check{f}_k = \left(\mathbf{D}^* \mathbf{F}^* \tilde{\mathbf{B}}^* \mathbf{f} \right)_k$$

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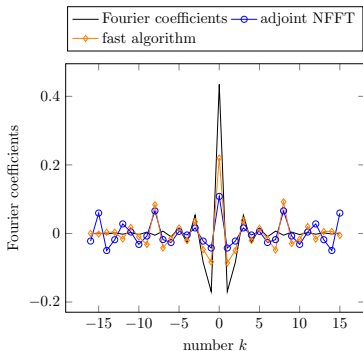
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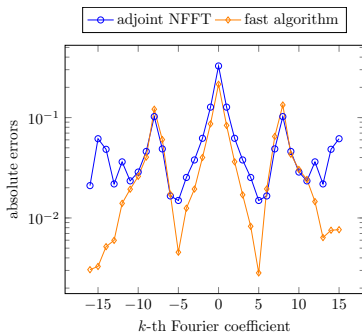
Reconstruction

- of $M = 32$ Fourier coefficients
- from function values $f(x_j)$ at jittered equispaced nodes x_j
- overdetermined as well as underdetermined
 - (a) $N = 8$
 - (b) $N = 128$

Inverse NFFT - underdetermined case

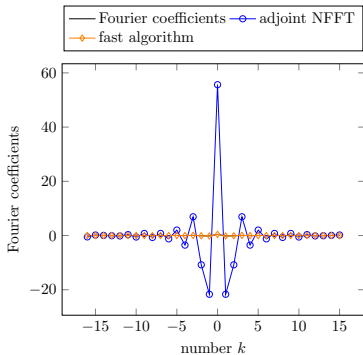


(a) reconstruction

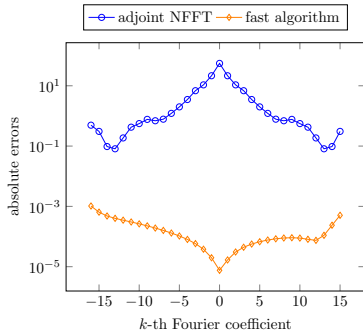


(b) pointwise errors

Inverse NFFT - overdetermined case



(a) reconstruction



(b) pointwise errors

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Consider again

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$$f(x_j) \approx \tilde{f}_j = \left(\frac{1}{M} \tilde{\mathbf{B}} \mathbf{F} \mathbf{D} \mathbf{f}\right)_j \quad \text{bzw.} \quad f(x_j) \approx \tilde{f}_j = \left(\tilde{\mathbf{B}} \mathbf{F} \mathbf{D} \mathbf{f}\right)_j$$

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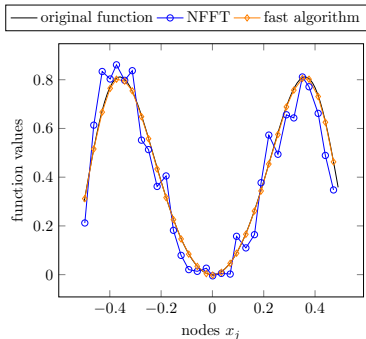
Reconstruction

- of $N = 32$ function values
- from Fourier coefficients \hat{f}_k
- overdetermined as well as underdetermined

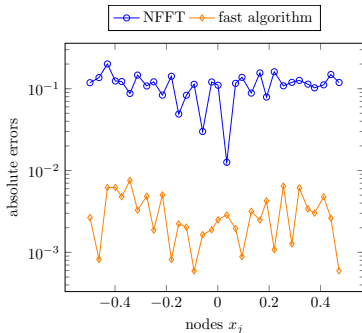
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(b) $M = 128$

Inverse adjoint NFFT - overdetermined case

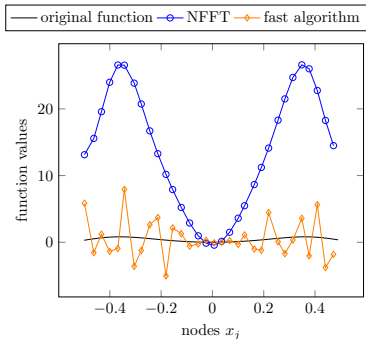


(a) reconstruction

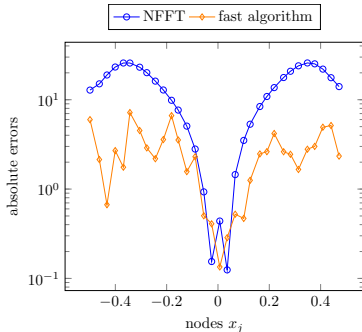


(b) pointwise errors

Inverse adjoint NFFT - underdetermined case




(a) reconstruction




(b) pointwise errors

Summary

- new direct method for general case
- iNFFT based on factorization BFD


optimized
- fast algorithms of complexity $\mathcal{O}(M \log M + N)$
- connection to frame-theoretical approach

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Thank you for your attention!