

1. Basics

- For the following matrices compute the eigenvalues, their algebraic and geometric multiplicities, their eigenvectors and, if needed, their generalized eigenvectors.

$$A = \begin{bmatrix} 2 & 1 \\ 4 & -1 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & -2 \\ 2 & 1 \end{bmatrix}, \quad C = \begin{bmatrix} 2 & 1 \\ -1 & 4 \end{bmatrix}, \quad D = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 3 & -4 \\ -2 & 1 & -2 \end{bmatrix},$$

$$E = \begin{bmatrix} 3 & -10 & -10 \\ 0 & 3 & 0 \\ 0 & -5 & -2 \end{bmatrix}, \quad F = \begin{bmatrix} 2 & 2 & 1 \\ 0 & 2 & 1 \\ 0 & -1 & 0 \end{bmatrix}$$

- „The big Six Matrix Decompositions“

Repeat the properties of the following matrix factorizations:

- 2.1. Cholesky-Decomposition
- 2.2. (Pivotised) LU-Decomposition
- 2.3. QR-Decomposition
- 2.4. Spectral Decomposition
- 2.5. Schur-Decomposition
- 2.6. Singular Value Decomposition (SVD)

Think about existence and uniqueness. Which algorithms you know for the decompositions ?

- Show the uniqueness of the sparse QR-Decomposition $A = Q_1 R_1$, if $A \in \mathbb{R}^{m \times n}$ ($m > n$) has full column rank. $Q_1 \in \mathbb{R}^{m \times n}$ has orthonormal columns and $R_1 \in \mathbb{R}^{n \times n}$ is a upper triangular matrix. Moreover, R_1 comes from the lower triangular factor G from the Cholesky-Decomposition of $A^T A$ by the identity $R_1 = G^T$.
- For $A \in \mathbb{R}^{m \times n}$ with $s = \text{rank}(A)$ we have the Singular Value Decomposition (SVD)

$$A = U \Sigma V^T$$

with orthonormal $U = [u_1, \dots, u_m] \in \mathbb{R}^{m \times m}$ and orthonormal $V = [v_1, \dots, v_n] \in \mathbb{R}^{n \times n}$.

Proof that:

- a) If $k < s$ and $A_k = \sum_{i=1}^k \sigma_i u_i v_i^T$, then:

$$\min_{\text{rank}(B)=k} \|A - B\|_2 = \|A - A_k\|_2 = \sigma_{k+1}$$

b)

$$\begin{aligned} \ker(A) &= \text{span}\{v_{s+1}, \dots, v_n\} \\ \text{im}(A) &= \text{span}\{u_1, \dots, u_s\} \end{aligned}$$

c)

$$\|A\|_F = \sqrt{\sigma_1^2 + \dots + \sigma_s^2}$$