

# Nonconvex Quadratic Programming

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# Outline



- 1 General QP
  - Introduction
  - Reformulation to LP with Complementarity Constraints
  - Bounding LP Relaxation
  
- 2 Special Case
  - Formulation
  - Valid Inequalities
  - Example
  
- 3 Fixed Cost Variables
  - Formulation
  - Lifting
  - Facets not from lifting

# Collaborators



- George Nemhauser (Georgia Institute of Technology) 
- Sam Burer (University of Iowa)  THE UNIVERSITY OF IOWA
- Tin-Chi Lin (University of Illinois U-C) 

# Outline



- 1 General QP
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Quadratic Program (QP):

$$\begin{aligned} \max \quad & \frac{1}{2}x^T Qx + c^T x \\ & Ax \leq b \end{aligned}$$

- If  $Q$  is negative semidefinite, then QP is solvable in polynomial time.
- If  $Q$  is indefinite, QP is  $\mathcal{NP}$ -hard.

# Reformulating QP



KKT conditions:

$$A^T y - Qx = c$$

$$Ax \leq b \quad y \geq 0$$

$$y^T (b - Ax) = 0$$

For any KKT point,

$$\frac{1}{2} x^T Qx + c^T x = \frac{1}{2} (c^T x + y^T b)$$

## Reformulation

$$\max \frac{1}{2} (c^T x + y^T b)$$

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# Just make it an IP



Slack variables  $s := b - Ax$

Can replace each complementarity  $y_i s_i = 0$  with

$$y_i \leq M \delta_i^y$$

$$s_i \leq M \delta_i^s$$

$$\delta_i^y + \delta_i^s \leq 1$$

$$\delta_i^y, \delta_i^s \in \{0, 1\}$$

for a sufficiently large  $M$ .

## Problems:

- Introduces many new variables
- big  $M$  yields poor LP relaxations
- Not as much fun



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# Direct Approach



Classic idea:

- solve LP relaxation
- branch on complementarity
- use branch-and-bound

$$\begin{aligned} \max \quad & \frac{1}{2} (c^T x + y^T b) \\ & A^T y - Qx = c \\ & Ax \leq b \quad y \geq 0 \end{aligned}$$

Other contexts

- Beale and Tomlin: SOS sets.
- Disjunctive Programs: Balas, Beaumont, etc...
- DeFarias and Nemhauser: complementarity, cardinality, SOS.

Challenges:

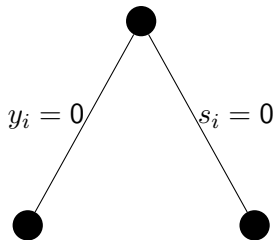
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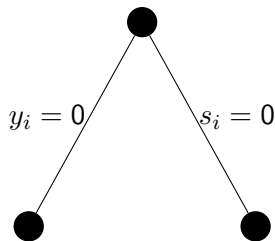
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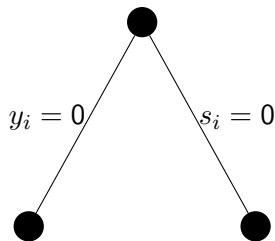
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# Bounding the LP relaxation



LP relaxation of complementarity reformulation:

$$\begin{aligned} \max \quad & \frac{1}{2} (c^T x + y^T b) \\ & A^T y - Qx = c \\ & Ax \leq b \quad y \geq 0 \end{aligned}$$

Assume  $\{x \in \mathbb{R}^n : Ax \leq b\}$  nonempty and bounded,  
i.e.  $\{r \in \mathbb{R}^n : Ar \leq 0\} = \{0\}$ .

Recession cone of the LP relaxation:

$$\begin{aligned} \mathcal{C} = \{(\gamma, r) \in \mathbb{R}^{m+n} : Ar \leq 0, A^T \gamma - Qr = 0, \gamma \geq 0\} = \\ \{(\gamma, 0) \in \mathbb{R}^{m+n} : A^T \gamma = 0, \gamma \geq 0\} \end{aligned}$$



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# Extreme rays of LP relaxation



$\exists$  interior point, i.e.  $\bar{x}$  such that  $A\bar{x} < b \Rightarrow$   
 $b^T \gamma > 0 \forall (\gamma, 0) \in \mathcal{C} \setminus \{0\}$

$\Rightarrow$  LP relaxation is unbounded.

If  $(y, x)$  is a feasible, complementary solution and  $(\gamma, 0) \in \mathcal{C} \setminus \{0\}$ , then

$$(y + t\gamma)^T (b - Ax) = t\gamma^T b > 0 \text{ for any } t > 0$$

- Convex hull of complementary solutions is closed and bounded
- Every vertex of this convex hull is a vertex of LP relaxation
- Optimize over just the vertices of the LP relaxation?
- Will not necessarily yield complementary solutions

Unfortunately, this is not easy in general

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# Complexity

## Observation

*Given an LP in the form of a poly-time separation oracle, optimizing an arbitrary linear objective function over the extreme points of this LP is  $\mathcal{NP}$ -hard.*

Dominant of convex hull of incidence vectors of  $s - t$  paths:

$$\left\{ x \in \mathbb{R}_+^{|E|} : a_H^T x \geq 1 \quad \forall H \in \mathcal{H} \right\}$$

- $\mathcal{H}$ : set of  $s - t$  cuts
- $a_H$ : incidence vector of a cut  $H$ .



Finding vertex that maximizes arbitrary linear objective



Longest Path



# Bounding LP relaxation



Need a way to "truncate" the polyhedron

$$A^T y - Qx = c$$

$$Ax \leq b$$

$$y \geq 0$$

without eliminating solutions that satisfy  $y^T(b - Ax) = 0$ .

- Could use information about sizes of vertices:  
vertex size  $\leq 4n^2 \times$  inequality size
- Add valid inequalities
- Examine special cases

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## QP with simple bounds



Quadratic program with simple bounds (QPB):

$$\begin{aligned} \max \quad & \frac{1}{2}x^T Qx + c^T x \\ & 0 \leq x \leq e \end{aligned}$$

- Can show this generalizes 0-1 QP
- $\mathcal{NP}$ -complete

## KKT reformulation



Equivalent complementarity problem:

$$\max \frac{1}{2}c^T x + \frac{1}{2}y^T e$$

$$y_i - \sum_{j \in N} q_{ij}x_j - z_i = c_i \quad \forall i \in N$$

$$y_i(1 - x_i) = 0 \quad \forall i \in N$$

$$z_i x_i = 0 \quad \forall i \in N$$

$$x \leq e \quad x, y, z \geq 0$$

$$y_i(1 - x_i) = 0 \text{ and } z_i x_i = 0 \Rightarrow y_i z_i = 0$$

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$$y_i(1 - x_i) = 0 \text{ and } z_i x_i = 0 \Rightarrow y_i z_i = 0$$



# Bounding the LP relaxation

$$\text{Row } i : y_i - z_i - \sum_{j \in N} q_{ij} x_j = c_i$$

Define

- $\bar{y}_i \equiv c_i + q_{ii} + \sum_{j \in N \setminus i} q_{ij}^+$
- $\bar{z}_i \equiv -c_i - \sum_{j \in N \setminus i} q_{ij}^-$

where  $a^+ = \max\{0, a\}$

where  $a^- = \min\{0, a\}$

- If  $y_i > 0$ , then  $y_i \leq \bar{y}_i$
- If  $z_i > 0$ , then  $z_i \leq \bar{z}_i$

Assume  $\bar{y}_i > 0$  and  $\bar{z}_i > 0$

Yields two sets of valid inequalities:

- $y_i \leq \bar{y}_i x_i$
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Make LP relaxation bounded



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# One-row relaxations



Find relaxations of the problem for which generating cuts is easy.

Consider the set

$$S_i \equiv \left\{ (y_i, z_i, x) \in \mathbb{R}^{n+2} : \begin{aligned} y_i - \sum_{j \in N} q_{ij} x_j - z_i &= c_i \\ y_i(1 - x_i) &= 0, z_i x_i = 0 \\ x_j \leq 1 \quad \forall j \in N, y_i, z_i, x &\geq 0 \end{aligned} \right\}$$

Want valid inequalities for  $\text{conv}(S_i)$ .

- Much like knapsack relaxation
- Only 2 non-convexities (unlike knapsack)



# Nontrivial facets

Facets not induced by bounds belong to one of two classes

- $z_i + \sum_j \alpha_j x_j \leq \sum_j \alpha_j^+$

$$\left. \begin{aligned} \sum_j |\alpha_j| &= \bar{z}_i \\ \alpha_i &\geq 0 \\ 0 \leq \alpha_j &\leq q_{ij} \quad \forall j \in N^+ \\ q_{ij} \leq \alpha_j &\leq 0 \quad \forall j \in N^- \end{aligned} \right\} SEP^z$$

- $y_i + \sum_j \alpha_j x_j \leq \sum_j \alpha_j^+$

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## Example (cont.)



Optimal solution to LP:

$$y^* = \begin{pmatrix} 0 \\ 2 \\ 7.5 \\ 2.5 \end{pmatrix} \quad z^* = \begin{pmatrix} 6 \\ 0.5 \\ 0 \\ 0 \end{pmatrix} \quad x^* = \begin{pmatrix} 0 \\ 0.5 \\ 1 \\ 1 \end{pmatrix}$$

Adding the following inequalities:

$$\begin{aligned} z_2 + x_4 &\leq 1 \\ y_2 - 3x_1 + x_3 &\leq 1 \end{aligned}$$

Cuts off the optimal LP solution and produces the optimal complementary solution.

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## ● Computational Issues

- Cuts can be separated in  $\mathcal{O}(n \log n)$
- To be effective, cuts must be added and deleted aggressively
- Use of cuts significantly expedites branch-and-bound
- Direct method much better than conversion to IP
- Strong branching very effective for "hard" instances
- Tables of computational results available for those interested (and can't find anything better to do)

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## ● Theoretical Issues

- Only vertices of  $SEP^*$  and  $SEP^U$  can yield facets
- Possible to identify which vertices yield facets
- Possible to characterize convex hull when  $\bar{y}_i \leq 0$  or  $\bar{z}_i \leq 0$

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- Only vertices of  $SEP^*$  and  $SEP^U$  can yield facets
- Possible to identify which vertices yield facets
- Possible to characterize convex hull when  $\bar{y}_i \leq 0$  or  $\bar{z}_i \leq 0$

# Comments



- Computational Issues

- Cuts can be separated in  $\mathcal{O}(n \log n)$
- To be effective, cuts must be added and deleted aggressively
- **Use of cuts significantly expedites branch-and-bound**
- Direct method much better than conversion to IP
- Strong branching very effective for "hard" instances
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# Outline



- 1 General QP
- 2 Special Case
- 3 Fixed Cost Variables
  - Formulation
  - Lifting
  - Facets not from lifting



# Fixed cost variables



Consider the problem

$$\begin{aligned} \max \quad & \frac{1}{2} x^T Q x + c^T x - f^T \delta \\ & 0 \leq x_j \leq \delta_j \quad \forall j \in N \\ & \delta_j \in \{0, 1\} \quad \forall j \in N \end{aligned}$$

Can reformulate as

$$\begin{aligned} \max \quad & \frac{1}{2} (c^T x + e^T y^1) - f^T \delta \\ & y^1 + y^0 - Qx - z = c \\ & y_i^1(1 - x_i) = 0 \quad y_i^0 x_i = 0 \quad z_i x_i = 0 \quad \forall i \in N \\ & 0 \leq x_j \leq \delta_j \quad \forall j \in N \quad \delta_j \in \{0, 1\} \quad \forall j \in N \\ & y^1, y^0, z \geq 0 \end{aligned}$$

WLOG, can also require that  $y_i^0 z_i = 0$ .

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# One-row relaxations

$$S_i \equiv \left\{ (y_i^1, y_i^0, z_i, x) \in \mathbb{R}^{n+2} : y_i^1 + y_i^0 - \sum_{j \in N} q_{ij} x_j - z_i = c_i \right. \\ \left. \begin{aligned} y_i^1(1 - x_i) = 0, y_i^0 x_i = 0, z_i x_i = 0 \\ x_j \leq 1 \forall j \in N, y_i^1, y_i^0, z_i, x \geq 0 \end{aligned} \right\}$$

## Projecting

$S_i|_{y_i^0=0}$  gives the one-row relaxation from before

## Definition

$$\bar{y}_i^0 := c_i + \sum_{j \in N^+} q_{ij}$$



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## Lifting



Facet of  $S_i|_{y_i^0=0}$ :  $z_i + \sum_j \alpha_j x_j \leq \sum_j \alpha_j^+$

$$\left. \begin{array}{l} \sum_j |\alpha_j| = \bar{z}_i \\ \alpha_i \geq 0 \\ 0 \leq \alpha_j \leq q_{ij} \quad \forall j \in N^+ \\ q_{ij} \leq \alpha_j \leq 0 \quad \forall j \in N^- \end{array} \right\} SEP^z$$

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$$\theta = \min \frac{\sum_j (\alpha_j^+ - \alpha_j x_j) - z_i}{y_i^0}$$

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## Lifting problem solution

$$\theta = \frac{\alpha_i}{\bar{y}_i^0}$$

$$z_i + \frac{\alpha_i}{\bar{y}_i^0} y_i^0 + \sum_j \alpha_j x_j \leq \sum_j \alpha_j^+$$

## Lifting (cont.)



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Set  $x_j = 1$  if  $\alpha_j > 0$  or if  $j \in N^+$  and  $\alpha_j = 0$

Feasible point if  $c_i + \sum_{j \in N^-: \alpha_j > 0} q_{ij} + \sum_{j \in N^+: \alpha_j = 0} q_{ij} > 0$

→ Necessary condition to be facet of  $S_i|_{y_i^0=0}$ .



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# Lifting (cont.)

## Lifting problem solution

$$\theta = 0$$

$$y_i^1 + \sum_j \alpha_j x_j \leq \sum_j \alpha_j^+$$

if original inequality is facet of  $S_i|_{y_i^0=0}$

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# Nontrivial Facets



Arbitrary Valid Inequality:

$$\alpha^{y^1} y_i^1 + \alpha^{y^0} y_i^0 + \alpha^z z_i + \sum_{j \in N} \alpha_j x_j \leq \beta$$

Eliminate  $y_i^1$  using equality set:

$$\alpha^{y^0} y_i^0 + \alpha^z z_i + \sum_{j \in N} \alpha_j x_j \leq \beta$$

Theorem

For any nontrivial facet,  $\alpha^z \geq 0$ .

Furthermore,  $\alpha^z = 0 \Rightarrow \alpha^{y^0} > 0$  and  $\alpha_i = 0$

Consider two cases

- $\alpha^z = 0$
- $\alpha^z > 0$

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$$y_i^0 + \sum_{j \neq i} \alpha_j \leq \sum_{j \neq i} \alpha_j^+$$

$$SEPy^0 := \left\{ \begin{array}{l} \sum_{j \neq i} |\alpha_j| = \bar{y}_i^0 \\ -q_{ij} \leq \alpha_j \leq 0 \quad \forall j \in N^+ \\ 0 \leq \alpha_j \leq -q_{ij} \quad \forall j \in N^- \end{array} \right\}$$

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Suppose  $\alpha$  is a vertex of  $SEPy^0$  and

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then inequality is a facet of  $\text{conv}(S_i)$ .





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$$\alpha^z > 0, \alpha_i < 0$$



$$z_i + \alpha^{y^0} y_i^0 + \sum_j \alpha_j x_j \leq \beta$$

Conjecture

$$\alpha_i < 0 \Rightarrow \alpha^{y^0} = -1$$

Use equality set to rewrite inequality as

$$y_i^1 + \sum_j \alpha_j x_j \leq \beta$$

- Consistent with lifting result
- Equivalent to  $y_i$ -inequalities from  $S_i|_{y_i^0=0}$
- Can use  $SEP^y$  to separate
- Nothing new and hence no fun



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$$\alpha_i < 0 \Rightarrow \alpha^{y^0} = -1$$

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### Definition

$$B^+ := \{j \in N^+ : \alpha_j < 0\}$$

$$B^- := \{j \in N^- : \alpha_j > 0\}$$

$$B = B^+ \cup B^-$$



# Necessary conditions

$$z_i + \alpha^{y^0} y_i^0 + \sum_j \alpha_j x_j \leq \beta$$

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# Facets



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## Theorem

If  $(\alpha^{y^0}, \alpha, \beta)$  is an extreme point, and

- $c_i + \sum_{j \in N^+ \setminus B} q_{ij} + \sum_{j \in B^-} q_{ij} > 0$
- $q_{ii} + c_i + \sum_{j \in N^+ \setminus B} q_{ij} + \sum_{j \in B^-} q_{ij} > 0,$

then it is a facet of  $S_i$ .

Some comments:

- Condition is also necessary.
- When  $B = \emptyset$ , gives facets which are lifted "non-facets".
- How to choose  $B$ ?

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